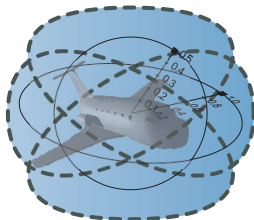


# Differential Equation Invariance Axiomatization

André Platzer   Yong Kiam Tan

**Carnegie Mellon University**

J. ACM **67**(1), 2020.



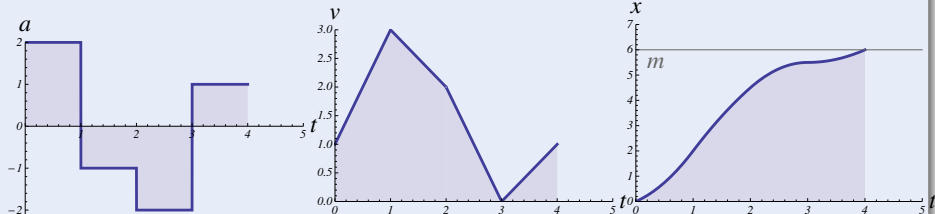
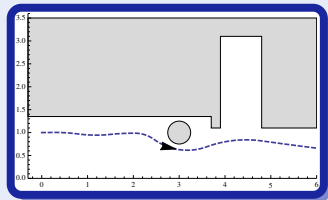


- 1 Differential Dynamic Logic
  - Syntax
  - Axiomatization
  - Relative Completeness / ODE
- 2 Proofs for Differential Equations
  - Differential Invariants / Cuts / Ghosts
- 3 Completeness for Differential Equation Invariants
  - Darboux are Differential Ghosts
  - Derived Differential Radical Invariants
  - Real Induction
  - Derived Local Progress
  - Completeness for Invariants
  - Completeness for Noetherian Functions
- 4 Summary

## Challenge (Hybrid Systems)

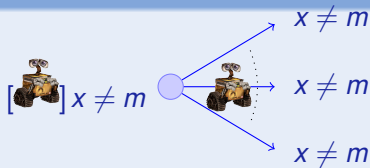
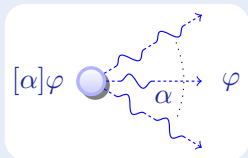
Fixed law describing state evolution with both

- Discrete dynamics (control decisions)
- Continuous dynamics (differential equations)



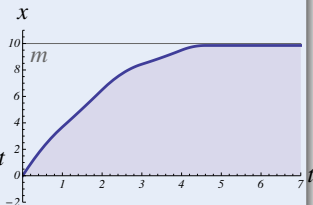
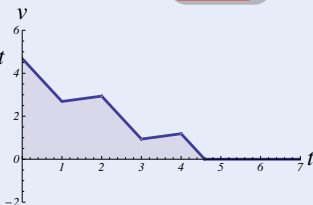
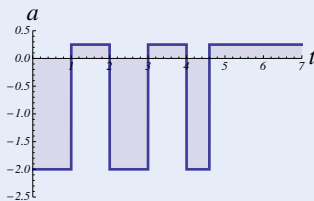
## Concept (Differential Dynamic Logic)

(JAR'08, LICS'12)

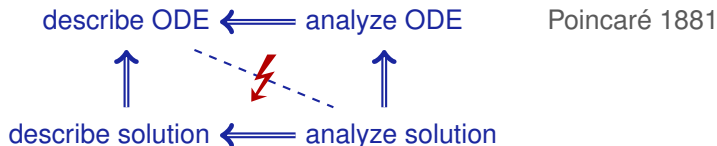


$$\underbrace{x \neq m \wedge b > 0}_{\text{init}} \rightarrow \left[ \left( \text{if}(\text{SB}(x, m)) \ a := -b \ ; \ x' = v, v' = a \right)^* \right] \underbrace{x \neq m}_{\text{post}}$$

all runs



- Classical approach: ① Given ODE ② Solve ODE ③ Analyze solution
- Descriptive power of ODEs: ODE much easier than its solution
- ⚡ Analyzing ODEs via their solutions undoes their descriptive power!



- ① Now: Logical foundations of differential equation invariants
- ② Identify axioms for differential equations
- ③ Completeness for differential equation invariants
- ④ Uniformly substitutable axioms, not infinite axiom schemata
- ⑤ Decide invariance by proof



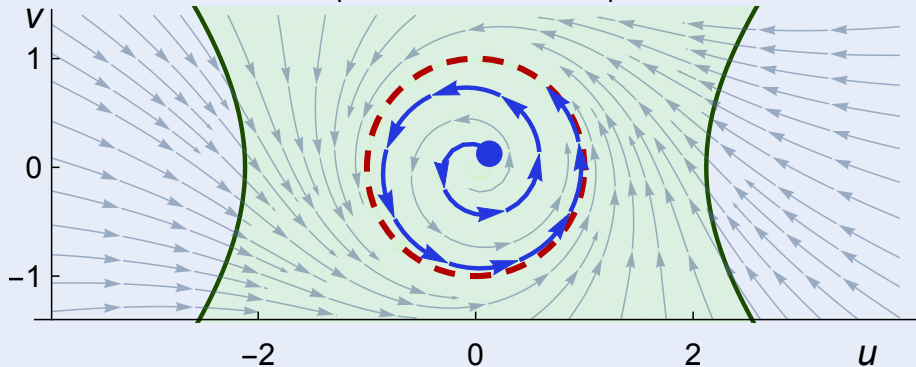
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Concept (Differential Dynamic Logic)

(JAR'08, LICS'12)

$$u^2 \leq v^2 + \frac{9}{2} \rightarrow [u' = -v + \frac{u}{4}(1 - u^2 - v^2), v' = u + \frac{v}{4}(1 - u^2 - v^2)] u^2 \leq v^2 + \frac{9}{2}$$

$$u^2 + v^2 = 1 \rightarrow [u' = -v + \frac{u}{4}(1 - u^2 - v^2), v' = u + \frac{v}{4}(1 - u^2 - v^2)] u^2 + v^2 = 1$$



Definition (Hybrid program  $\alpha$ )

$$\alpha, \beta ::= x := f(x) \mid ?Q \mid x' = f(x) \& Q \mid \alpha \cup \beta \mid \alpha; \beta \mid \alpha^*$$

Definition (dL Formula  $P$ )

$$P, Q ::= e \geq \tilde{e} \mid \neg P \mid P \wedge Q \mid \forall x P \mid \exists x P \mid [\alpha]P \mid \langle \alpha \rangle P$$



Discrete  
Assign

Test  
Condition

Differential  
Equation

Nondet.  
Choice

Seq.  
Compose

Nondet.  
Repeat

Definition (Hybrid program  $\alpha$ )

$$\alpha, \beta ::= x := f(x) \mid ?Q \mid x' = f(x) \& Q \mid \alpha \cup \beta \mid \alpha; \beta \mid \alpha^*$$

Definition (dL Formula  $P$ )

$$P, Q ::= e \geq \tilde{e} \mid \neg P \mid P \wedge Q \mid \forall x P \mid \exists x P \mid [\alpha]P \mid \langle \alpha \rangle P$$

All  
Reals

Some  
Reals

All  
Runs

Some  
Runs

$$[:=] \quad [x := e]p(x) \leftrightarrow p(e)$$

equations of truth

$$[?] \quad [?Q]P \leftrightarrow (Q \rightarrow P)$$

$$['] \quad [x' = f(x)]p(x) \leftrightarrow \forall t \geq 0 [x := y(t)]p(x) \quad (y'(t) = f(y))$$

$$[\cup] \quad [\alpha \cup \beta]P \leftrightarrow [\alpha]P \wedge [\beta]P$$

$$[;] \quad [\alpha; \beta]P \leftrightarrow [\alpha][\beta]P$$

$$[*] \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha][\alpha^*]P$$

$$K \quad [\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$$

$$I \quad [\alpha^*](P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$$

$$C \quad [\alpha^*]\forall v > 0 (P(v) \rightarrow \langle \alpha \rangle P(v-1)) \rightarrow \forall v (P(v) \rightarrow \langle \alpha^* \rangle \exists v \leq 0 P(v))$$

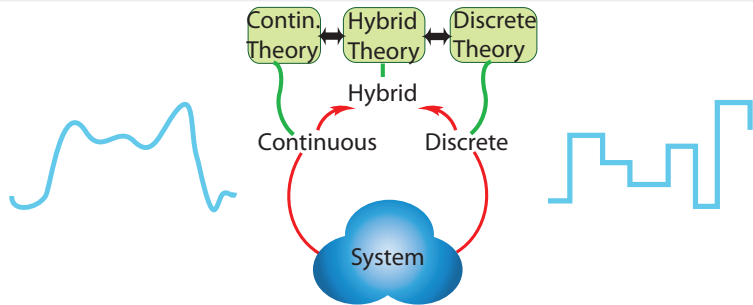
Theorem (Sound & Complete)

(JAR'08, LICS'12, JAR'17)

dL calculus is a sound & complete axiomatization of hybrid systems relative to either differential equations **or** relative to discrete dynamics.

Corollary (Complete Proof-theoretical Bridge)

proving continuous = proving hybrid = proving discrete

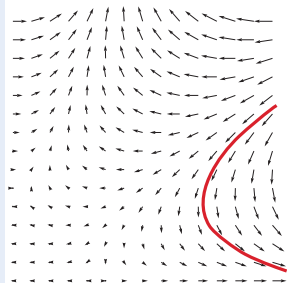




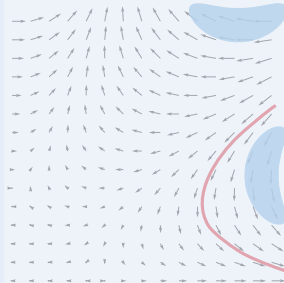
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# A Differential Invariants for Differential Equations

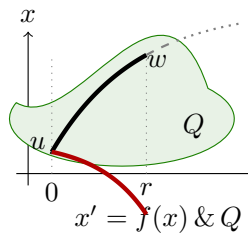
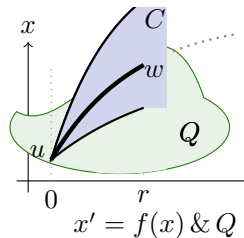
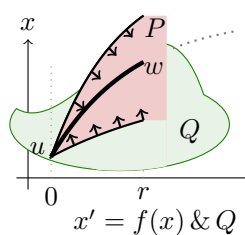
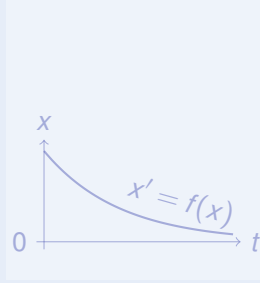
## Differential Invariant



## Differential Cut

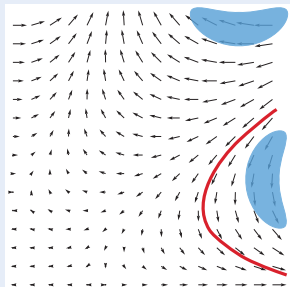


## Differential Ghost

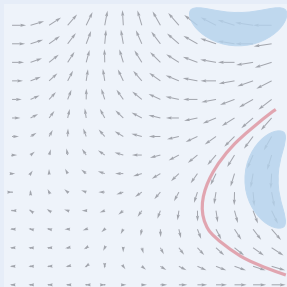


# A Differential Invariants for Differential Equations

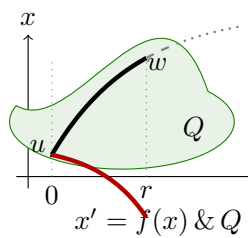
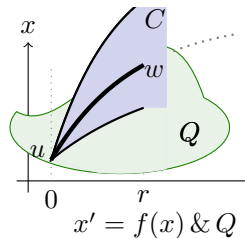
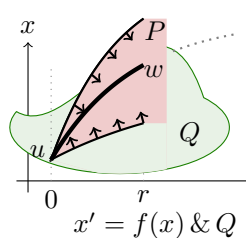
## Differential Invariant



## Differential Cut

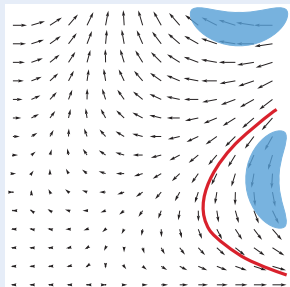


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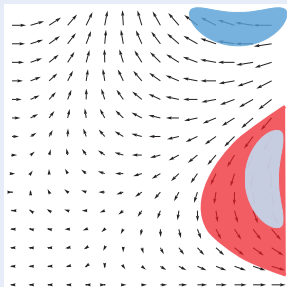


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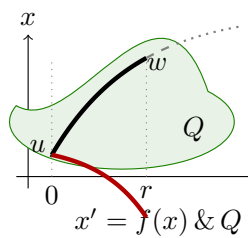
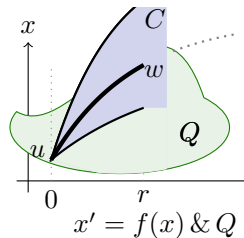
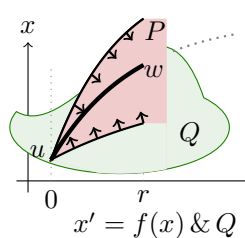
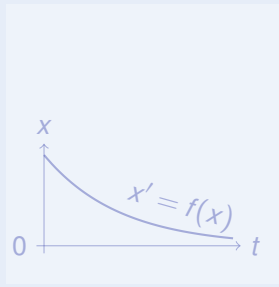
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## Differential Cut

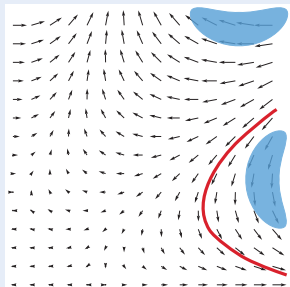


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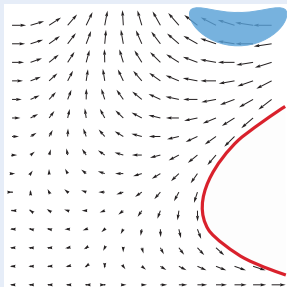


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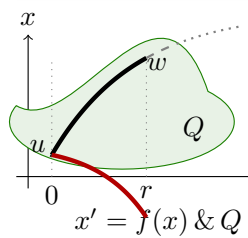
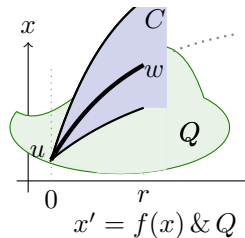
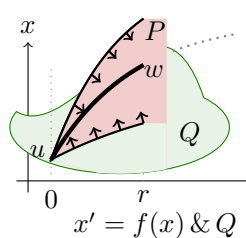
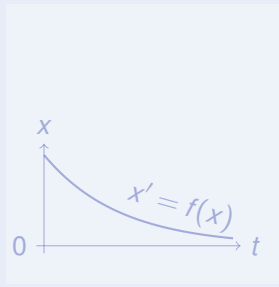
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## Differential Cut



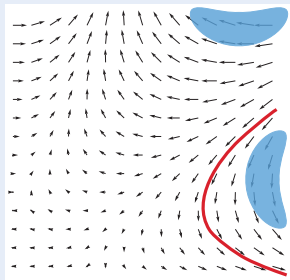
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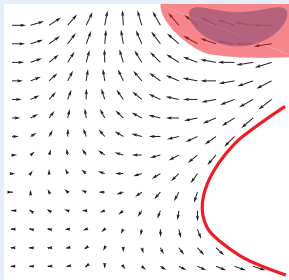


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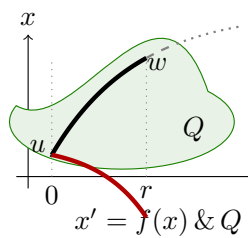
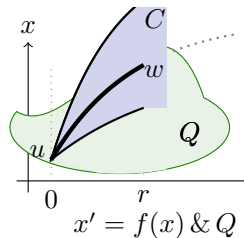
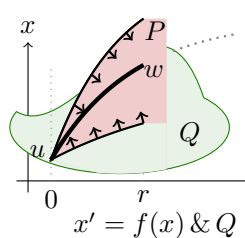
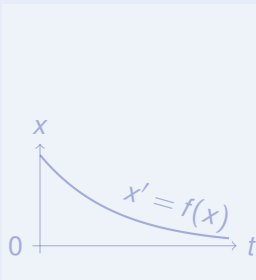
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## Differential Cut

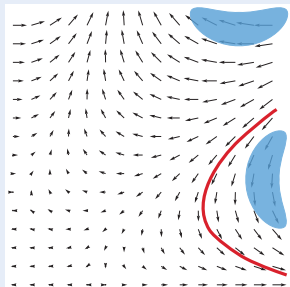


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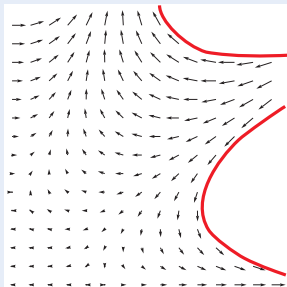


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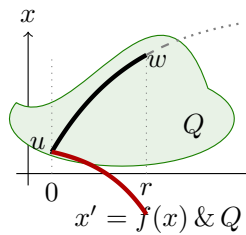
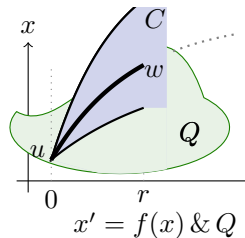
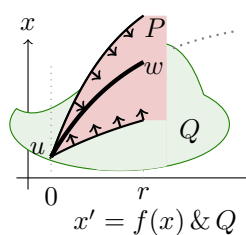
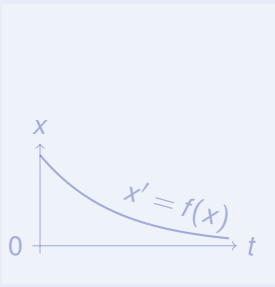
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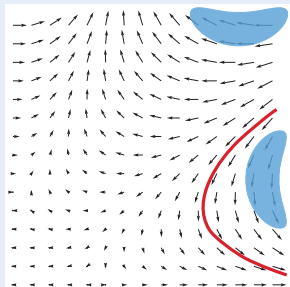


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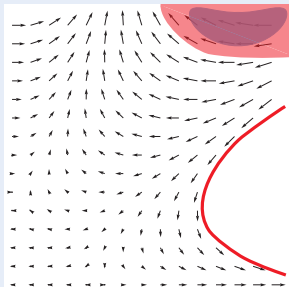


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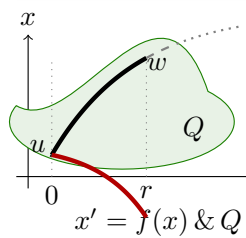
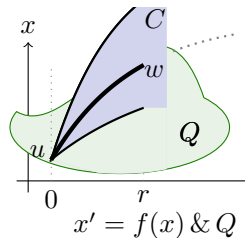
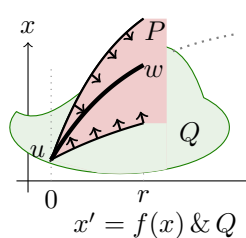
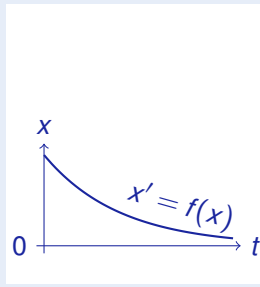
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## Differential Cut

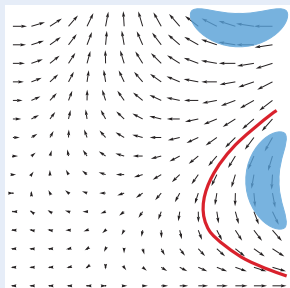


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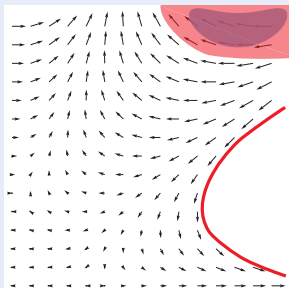


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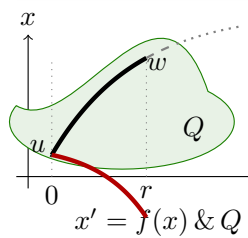
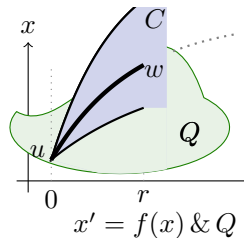
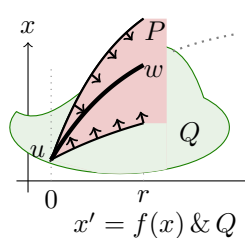
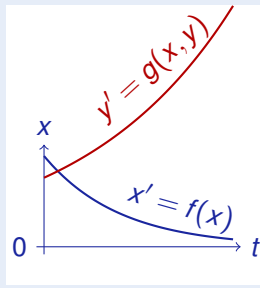
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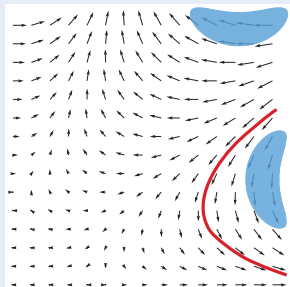


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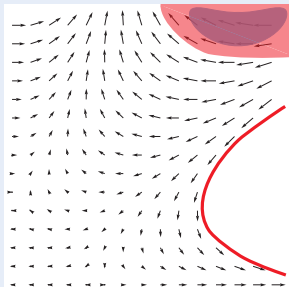


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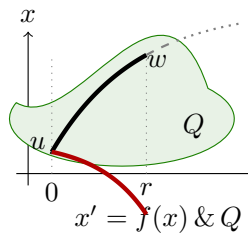
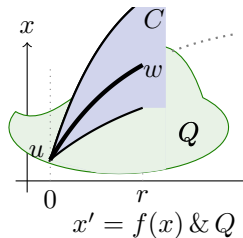
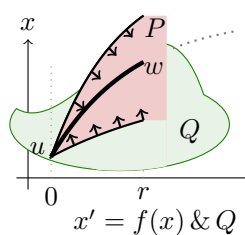
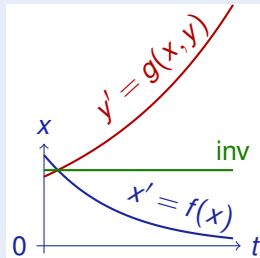
## Differential Invariant



## Differential Cut



## Differential Ghost



# A Differential Invariants for Differential Equations

## Differential Invariant

$$\frac{Q \rightarrow [x' := f(x)](P)'}{P \rightarrow [x' = f(x) \& Q]P}$$

## Differential Cut

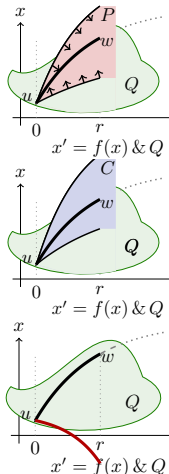
$$\frac{P \rightarrow [x' = f(x) \& Q]C \quad P \rightarrow [x' = f(x) \& Q \wedge C]P}{P \rightarrow [x' = f(x) \& Q]P}$$

## Differential Ghost

$$\frac{P \leftrightarrow \exists y G \quad G \rightarrow [x' = f(x), y' = g(x, y) \& Q]G}{P \rightarrow [x' = f(x) \& Q]P}$$

deductive power added  $DI \prec DI+DC \prec DI+DC+DG$

$$\llbracket (e)' \rrbracket_v = \sum_x v(x') \frac{\partial \llbracket e \rrbracket}{\partial x}(v)$$



# $\mathcal{A}$ Differential Invariants for Differential Equations

## Differential Invariant

$$\frac{Q \rightarrow [x' := f(x)](P)'}{P \rightarrow [x' = f(x) \& Q]P}$$

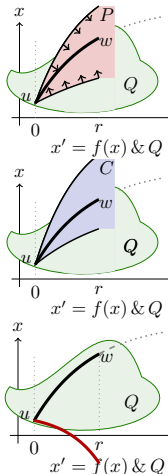
## Differential Cut

$$\frac{P \rightarrow [x' = f(x) \& Q]C \quad P \rightarrow [x' = f(x) \& Q \wedge C]P}{P \rightarrow [x' = f(x) \& Q]P}$$

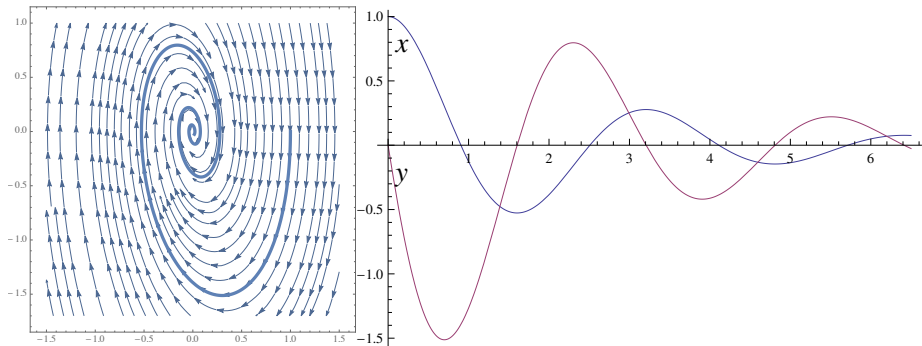
## Differential Ghost

$$\frac{P \leftrightarrow \exists y G \quad G \rightarrow [x' = f(x), y' = g(x, y) \& Q]G}{P \rightarrow [x' = f(x) \& Q]P}$$

if  $g(x, y) = a(x)y + b(x)$ , so has long solution!

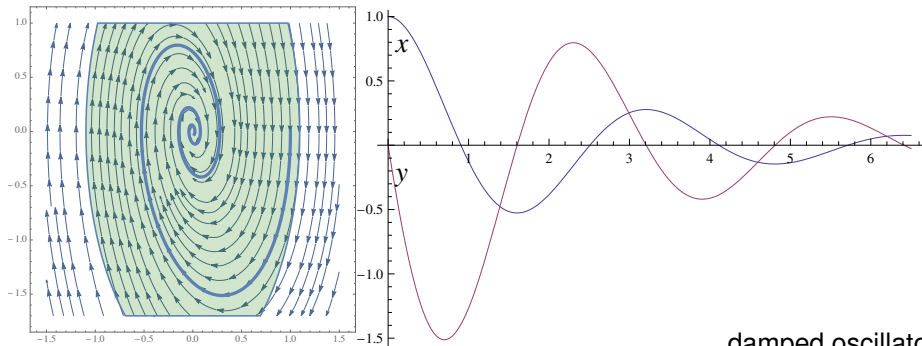


$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \ \omega^2 x^2 + y^2 \leq c^2$$





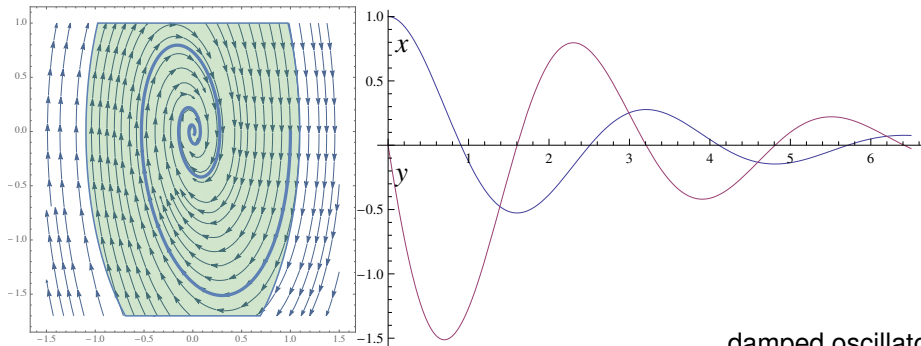
$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \ \omega^2 x^2 + y^2 \leq c^2$$



damped oscillator

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 x x' + 2y y' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

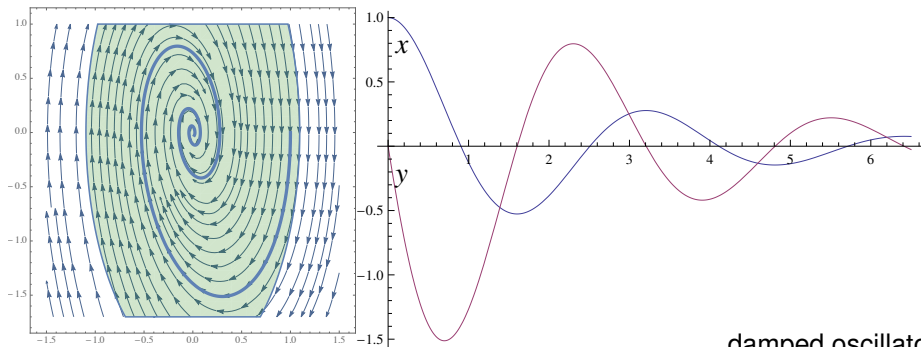


damped oscillator

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 x y + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 x x' + 2y y' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$



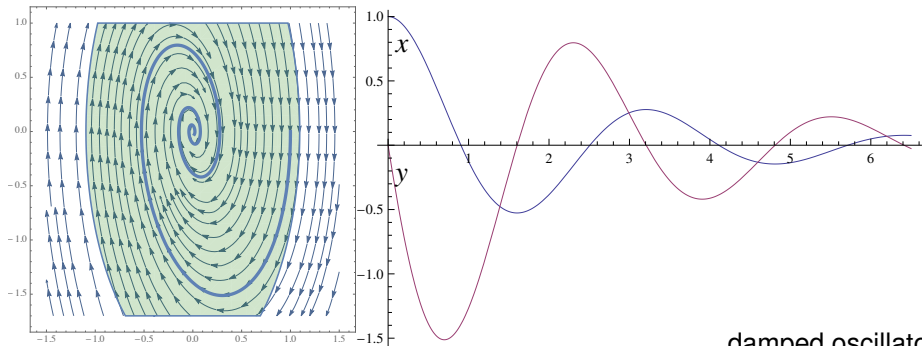
damped oscillator

\*

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 xy + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 xx' + 2yy' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$



damped oscillator

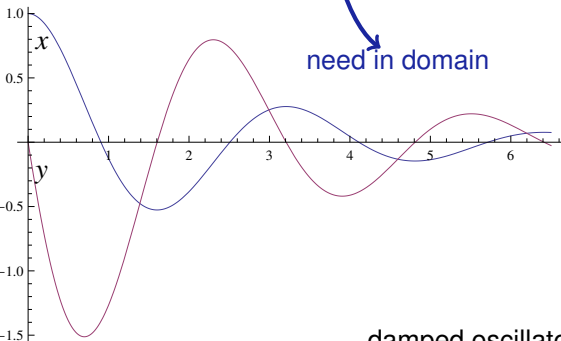
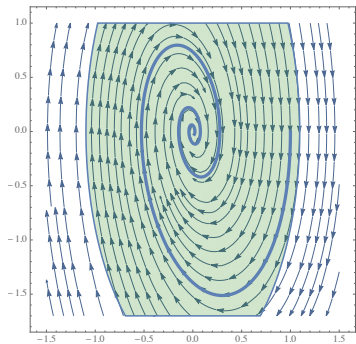


\*

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 xy + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 x x' + 2y y' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$



damped oscillator

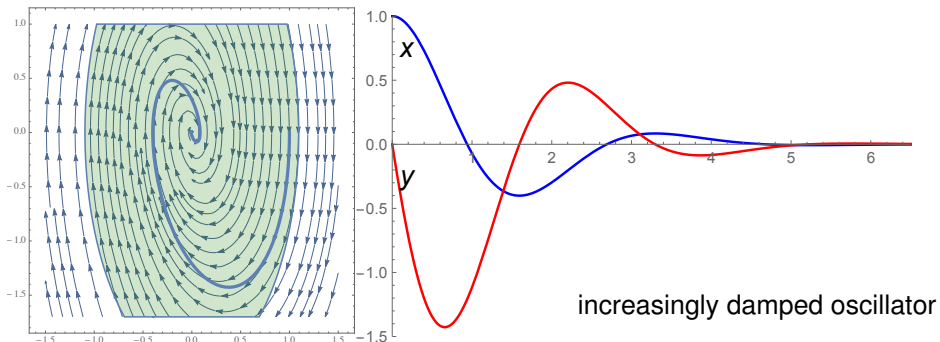


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$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2$$



$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \ \omega^2 x^2 + y^2 \leq c^2$$



$$\overline{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

$$\overline{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

increasingly damped oscillator



$$\frac{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2}{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

ask

$$\frac{d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0}{d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0}$$

increasingly damped oscillator

$$\frac{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2}{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

$$\frac{\omega \geq 0 \rightarrow [d' := 7] d' \geq 0}{d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0}$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator

$$\frac{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2}{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

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$$\omega \geq 0 \rightarrow d \geq 0$$

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$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

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$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator

$$\frac{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \ \& \ d \geq 0] \omega^2 x^2 + y^2 \leq c^2}{\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2}$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

DC

\*

$$\frac{\omega \geq 0 \rightarrow 7 \geq 0}{\omega \geq 0 \rightarrow [d' := 7] d' \geq 0}$$

$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 x x' + 2y y' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

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\*

$$\omega \geq 0 \rightarrow 7 \geq 0$$

$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 x y + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

$$\omega \geq 0 \wedge d \geq 0 \rightarrow [x' := y][y' := -\omega^2 x - 2d\omega y] 2\omega^2 x x' + 2y y' \leq 0$$

$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0 \wedge d \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

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\*

$$\omega \geq 0 \rightarrow 7 \geq 0$$

$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator



\*

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 xy + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

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\*

$$\omega \geq 0 \rightarrow 7 \geq 0$$

$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

increasingly damped oscillator



\*

$$\omega \geq 0 \wedge d \geq 0 \rightarrow 2\omega^2 xy + 2y(-\omega^2 x - 2d\omega y) \leq 0$$

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$$\omega^2 x^2 + y^2 \leq c^2 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] \omega^2 x^2 + y^2 \leq c^2$$

init

\*

$$\omega \geq 0 \rightarrow 7 \geq 0$$

$$\omega \geq 0 \rightarrow [d' := 7] d' \geq 0$$

$$d \geq 0 \rightarrow [x' = y, y' = -\omega^2 x - 2d\omega y, d' = 7 \ \& \ \omega \geq 0] d \geq 0$$

Could repeatedly diffcut in formulas to help the proof





- 1 Differential Dynamic Logic
  - Syntax
  - Axiomatization
  - Relative Completeness / ODE
- 2 Proofs for Differential Equations
  - Differential Invariants / Cuts / Ghosts
- 3 **Completeness for Differential Equation Invariants**
  - Darboux are Differential Ghosts
  - Derived Differential Radical Invariants
  - Real Induction
  - Derived Local Progress
  - Completeness for Invariants
  - Completeness for Noetherian Functions
- 4 Summary

Theorem (Algebraic Completeness)

(LICS'18,JACM'20)

*dL calculus is a sound & complete axiomatization of algebraic invariants of polynomial differential equations. They are decidable by DI,DC,DG in dL.*

Theorem (Semialgebraic Completeness)

(LICS'18,JACM'20)

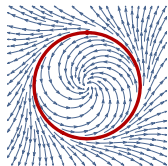
*dL calculus with RI is a sound & complete axiomatization of semialgebraic invariants of differential equations. They are decidable in dL.*

Darboux equalities are DG

Gaston Darboux 1878

$(g \in \mathbb{R}[x])$

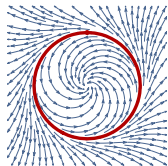
$$\frac{Q \rightarrow e' = ge}{e = 0 \rightarrow [x' = f(x) \& Q] e = 0}$$



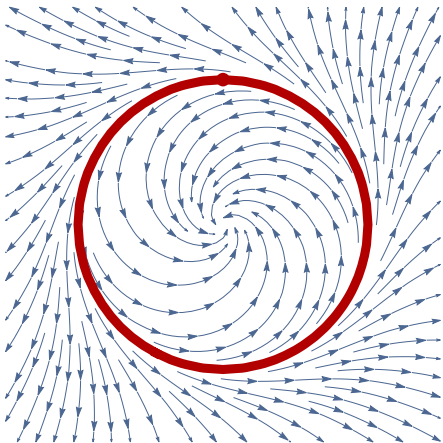
Definable  $e'$  for Lie-derivative w.r.t. ODE

Darboux equalities are DG

Gaston Darboux 1878



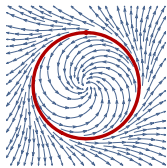
$$\frac{Q \rightarrow e' = ge}{e = 0 \rightarrow [x' = f(x) \& Q]e = 0} \quad (g \in \mathbb{R}[x])$$



$$\begin{aligned} \rightarrow 2uu' + 2vv' &= 2(u^2 + v^2)(u^2 + v^2 - 1) \\ \dots \rightarrow [u' &= -v - u + u^3 + uv^2 \\ v' &= u - v + u^2v + v^3] u^2 + v^2 - 1 = 0 \end{aligned}$$

Darboux equalities are DG

$$\frac{Q \rightarrow e' = ge}{e = 0 \rightarrow [x' = f(x) \& Q]e = 0} \quad (g \in \mathbb{R}[x])$$



Proof Idea.

- 1 DG counterweight  $y' = -gy$  to reduce  $e = 0$  to  $ey = 0 \wedge y \neq 0$ .
- 2 DG counter-counterweight  $z' = gz$  to reduce  $y \neq 0$  to  $yz = 1$ .
- 3  $ey = 0$  and  $yz = 1$  are now differential invariants by construction. □

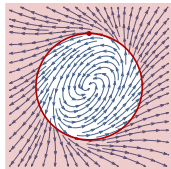
Derive  $[x' = f(x) \& Q](e)' = ge \rightarrow (e = 0 \rightarrow [x' = f(x) \& Q]e = 0)$

Darboux **ine**qualities are DG

Thomas Grönwall 1919

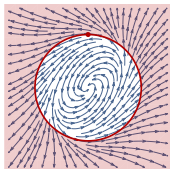
$(g \in \mathbb{R}[x])$

$$\frac{Q \rightarrow e' \geq ge}{e \succcurlyeq 0 \rightarrow [x' = f(x) \& Q] e \succcurlyeq 0}$$



Darboux **ine**qualities are DG

$$\frac{Q \rightarrow e' \geq ge}{e \succcurlyeq 0 \rightarrow [x' = f(x) \& Q]e \succcurlyeq 0} \quad (g \in \mathbb{R}[x])$$



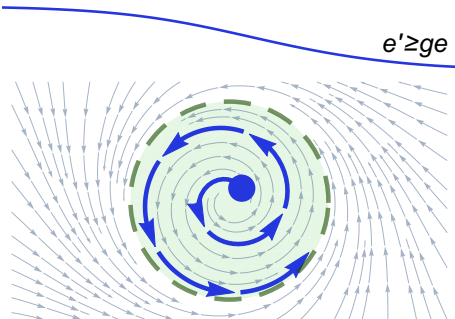
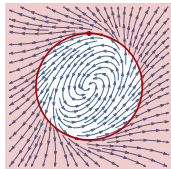
Proof Idea.

- 1 DG counterweight  $y' = -gy$  to reduce  $e \succcurlyeq 0$  to  $ey \succcurlyeq 0 \wedge y > 0$ .
- 2 DG counter-counterweight  $z' = \frac{g}{2}z$  to reduce  $y > 0$  to  $yz^2 = 1$ .
- 3  $yz^2 = 1$  and (after DC with  $y > 0$ )  $ey \succcurlyeq 0$  are differential invariants by construction as  $(ey)' = e'y - gye \geq 0$  from premise since  $y > 0$ . □

Derive  $[x' = f(x) \& Q](e)' \geq ge \rightarrow (e \succcurlyeq 0 \rightarrow [x' = f(x) \& Q]e \succcurlyeq 0)$

Darboux **ine**qualities are DG

$$\frac{Q \rightarrow e' \geq ge}{e \succcurlyeq 0 \rightarrow [x' = f(x) \& Q] e \succcurlyeq 0} \quad (g \in \mathbb{R}[x])$$

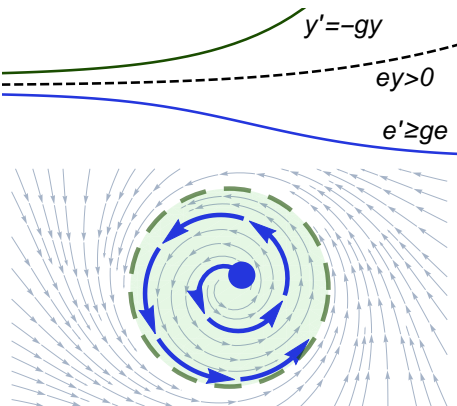
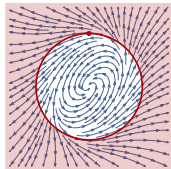


$$\begin{aligned} (1-u^2-v^2)' &\geq -\frac{1}{2}(u^2+v^2)(1-u^2-v^2) \\ \dots \rightarrow &\left[ \begin{aligned} u' &= -v + \frac{u}{4}(1-u^2-v^2) \\ v' &= u + \frac{v}{4}(1-u^2-v^2) \end{aligned} \right. \\ &\quad \left. \vphantom{\dots \rightarrow} 1-u^2-v^2 > 0 \right] \end{aligned}$$



Darboux **ine**qualities are DG

$$\frac{Q \rightarrow e' \geq ge}{e \succ 0 \rightarrow [x' = f(x) \& Q] e \succ 0} \quad (g \in \mathbb{R}[x])$$

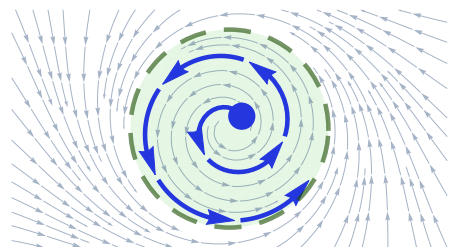
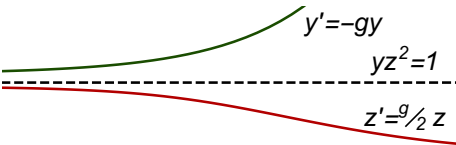
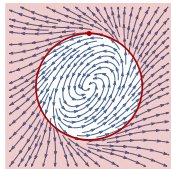


$$\begin{aligned} (1-u^2-v^2)' &\geq -\frac{1}{2}(u^2+v^2)(1-u^2-v^2) \\ \dots \rightarrow \left[ \begin{aligned} u' &= -v + \frac{u}{4}(1-u^2-v^2) \\ v' &= u + \frac{v}{4}(1-u^2-v^2) \\ y' &= \frac{1}{2}(u^2+v^2)y \end{aligned} \right. \\ &\quad \left. 1-u^2-v^2 > 0 \right] \end{aligned}$$

$$(1-u^2-v^2)y > 0$$

Darboux **ine**qualities are DG

$$\frac{Q \rightarrow e' \geq ge}{e \succ 0 \rightarrow [x' = f(x) \& Q]e \succ 0} \quad (g \in \mathbb{R}[x])$$



$$\begin{aligned} (1-u^2-v^2)' &\geq -\frac{1}{2}(u^2+v^2)(1-u^2-v^2) \\ \dots \rightarrow &\left[ \begin{aligned} u' &= -v + \frac{u}{4}(1-u^2-v^2) \\ v' &= u + \frac{v}{4}(1-u^2-v^2) \\ y' &= \frac{1}{2}(u^2+v^2)y \\ z' &= -\frac{1}{4}(u^2+v^2)z \end{aligned} \right. \\ &\left. \begin{aligned} &1-u^2-v^2 > 0 \\ &(1-u^2-v^2)y > 0 \\ &y z^2 = 1 \end{aligned} \right. \end{aligned}$$

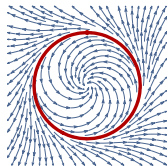
$$\begin{array}{c}
 * \\
 \hline
 \text{R} \quad Q \rightarrow (-gy)z^2 + y(2z(\frac{g}{2}z)) = 0 \\
 \hline
 \text{dl} \quad yz^2 = 1 \rightarrow [x' = f(x), y' = -gy, z' = \frac{g}{2}z \ \& \ Q] yz^2 = 1 \\
 \hline
 \text{M,}\exists\text{R} \quad y > 0 \rightarrow \exists z [x' = f(x), y' = -gy, z' = \frac{g}{2}z \ \& \ Q] y > 0 \\
 \hline
 \text{dG} \quad y > 0 \rightarrow [x' = f(x), y' = -gy \ \& \ Q] y > 0
 \end{array}$$

$$\begin{array}{c}
 * \\
 \hline
 Q \rightarrow e' \geq ge \quad \text{R} \quad e' \geq ge, y > 0 \rightarrow e'y - gye \geq 0 \\
 \hline
 \text{cut} \quad Q, y > 0 \rightarrow e'y - gye \geq 0 \\
 \hline
 \text{dl} \quad e \succcurlyeq 0, y > 0 \rightarrow [x' = f(x), y' = -gy \ \& \ Q \wedge y > 0] ey \succcurlyeq 0 \triangleright \\
 \hline
 \text{dC} \quad e \succcurlyeq 0, y > 0 \rightarrow [x' = f(x), y' = -gy \ \& \ Q] (y > 0 \wedge ey \succcurlyeq 0) \\
 \hline
 \text{M,}\exists\text{R} \quad e \succcurlyeq 0 \rightarrow \exists y [x' = f(x), y' = -gy \ \& \ Q] e \succcurlyeq 0 \\
 \hline
 \text{dG} \quad e \succcurlyeq 0 \rightarrow [x' = f(x) \ \& \ Q] e \succcurlyeq 0
 \end{array}$$

P.S.  $z' = \frac{g}{2}z$  superfluous for open inequalities  $e > 0$  and  $e \neq 0$ .

Vectorial Darboux are DG

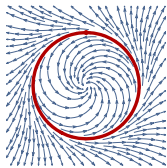
$$\frac{Q \rightarrow \mathbf{e}' = G\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0} \quad (G \in \mathbb{R}[x]^{n \times n})$$



Definable  $\mathbf{e}'$  for component-wise Lie-derivative w.r.t. ODE

Vectorial Darboux are DG

$$\frac{Q \rightarrow \mathbf{e}' = G\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0} \quad (G \in \mathbb{R}[x]^{n \times n})$$

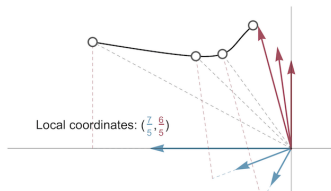
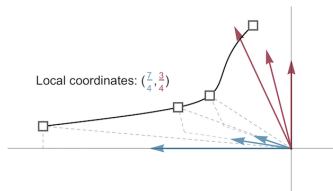
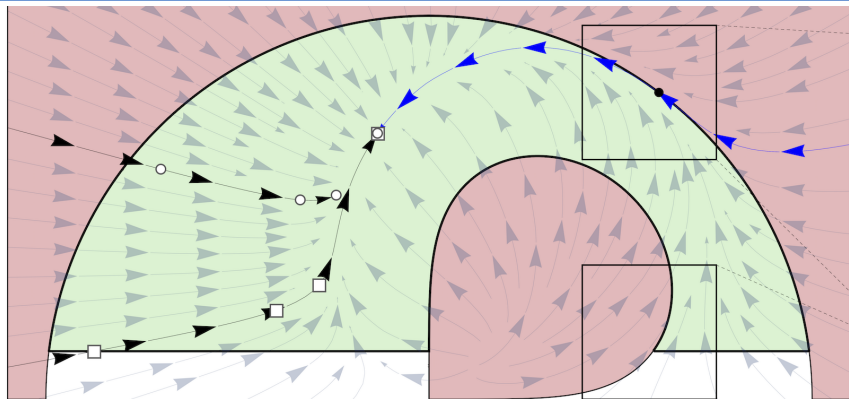


Proof Idea.

- 1 DG counterweight  $\mathbf{y}' = -G^T \mathbf{y}$  to change  $\mathbf{e} = 0$  to  $\mathbf{e} \cdot \mathbf{y} = 0$ .
- 2 But:  $\mathbf{e} \cdot \mathbf{y} = 0 \not\Rightarrow \mathbf{e} = 0$  even if  $\mathbf{y} \neq 0$ .
- 3 Redo: time-varying independent DG matrix  $Y' = -YG$  with  $Y\mathbf{e} = 0$ .
- 4  $Y\mathbf{e} = 0 \Rightarrow \mathbf{e} = 0$  if  $\det Y \neq 0$ .
- 5 DC  $\det Y \neq 0$  proves by dbx with Liouville:  $\det(Y)' = -\text{tr}(G)\det(Y)$
- 6 Continuous change of basis  $Y^{-1}$  balancing out motion of  $\mathbf{e}$ : constant!
- 7 Continuous change to new evolving variables is sound by DG. □

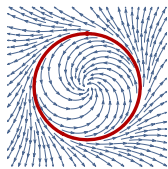
Derive  $[x' = f(x) \& Q](\mathbf{e}') = G\mathbf{e} \rightarrow (\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0)$

$\mathcal{A}$  Time is defined so that motion looks simple  $\approx$  Poincaré



Vectorial Darboux are DG

$$\frac{Q \rightarrow \mathbf{e}' = \mathbf{G}\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0} \quad (G \in \mathbb{R}[x]^{n \times n})$$



Proof Idea.

	*
R	$(\mathbf{e}') = \mathbf{G}\mathbf{e} \rightarrow -2\mathbf{e} \cdot (\mathbf{e}') \geq g(-\ \mathbf{e}\ ^2)$
( )'	$(\mathbf{e}') = \mathbf{G}\mathbf{e} \rightarrow (-\ \mathbf{e}\ ^2)' \geq g(-\ \mathbf{e}\ ^2)$
M	$[x' = f(x) \& Q](\mathbf{e}') = \mathbf{G}\mathbf{e} \rightarrow [x' = f(x) \& Q](-\ \mathbf{e}\ ^2)' \geq g(-\ \mathbf{e}\ ^2)$
DBX	$[x' = f(x) \& Q](\mathbf{e}') = \mathbf{G}\mathbf{e}, -\ \mathbf{e}\ ^2 \geq 0 \rightarrow [x' = f(x) \& Q]-\ \mathbf{e}\ ^2 \geq 0$
M	$[x' = f(x) \& Q](\mathbf{e}') = \mathbf{G}\mathbf{e}, \mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0$

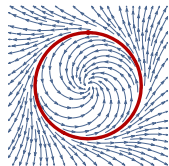
where  $g \stackrel{\text{def}}{=} 1 + \sum_{i=1}^n \sum_{j=1}^n G_{ij}^2$  1 + squared Frobenius  $\square$

Derive  $[x' = f(x) \& Q](\mathbf{e}') = \mathbf{G}\mathbf{e} \rightarrow (\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0)$

Vectorial Darboux are DG

$$Q \rightarrow \mathbf{e}' = G\mathbf{e}$$

$$\frac{}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$





Vectorial Darboux are DG

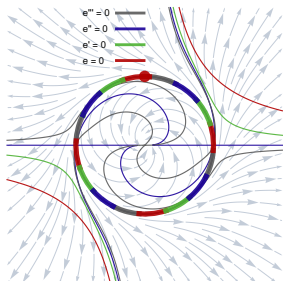
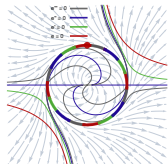
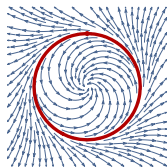
$$Q \rightarrow \mathbf{e}' = G\mathbf{e}$$

$$\frac{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q] \mathbf{e} = 0}{}$$

Differential Radical Invariants are DG

$$\Gamma, Q \rightarrow \bigwedge_{i=0}^{N-1} e^{(i)} = 0 \quad Q \rightarrow e^{(N)} = \sum_{i=0}^{N-1} g_i e^{(i)}$$

$$\frac{\Gamma \rightarrow [x' = f(x) \& Q] \mathbf{e} = 0}{}$$

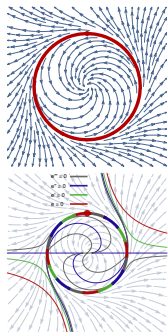


Vectorial Darboux are DG

$$\frac{Q \rightarrow \mathbf{e}' = G\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$

Differential Radical Invariants are DG

$$\frac{\Gamma, Q \rightarrow \bigwedge_{i=0}^{N-1} e^{(i)} = 0 \quad Q \rightarrow e^{(N)} = \sum_{i=0}^{N-1} g_i e^{(i)}}{\Gamma \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$



Proof Idea.

$$\text{by vdbx with } G = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & \ddots & \ddots & \vdots \\ \vdots & \vdots & \ddots & \ddots & 0 \\ 0 & 0 & \dots & 0 & 1 \\ g_0 & g_1 & \dots & g_{N-2} & g_{N-1} \end{pmatrix}, \quad \mathbf{e} = \begin{pmatrix} e \\ e^{(1)} \\ e^{(2)} \\ \vdots \\ e^{(N-1)} \end{pmatrix}$$

□

Vectorial Darboux are DG

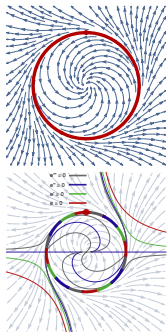
$$\frac{Q \rightarrow \mathbf{e}' = G\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$

Differential Radical Invariants are DG

$$\frac{\Gamma, Q \rightarrow \bigwedge_{i=0}^{N-1} e^{(i)} = 0 \quad Q \rightarrow e^{(N)} = \sum_{i=0}^{N-1} g_i e^{(i)}}{\Gamma \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$

$e'^* = 0$

$N$  exists



Vectorial Darboux are DG

$$\frac{Q \rightarrow \mathbf{e}' = G\mathbf{e}}{\mathbf{e} = 0 \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$

Differential Radical Invariants are DG

$$\frac{\Gamma, Q \rightarrow \bigwedge_{i=0}^{N-1} \mathbf{e}^{(i)} = 0 \quad Q \rightarrow \mathbf{e}^{(N)} = \sum_{i=0}^{N-1} g_i \mathbf{e}^{(i)}}{\Gamma \rightarrow [x' = f(x) \& Q]\mathbf{e} = 0}$$

$\mathbf{e}'^* = 0$

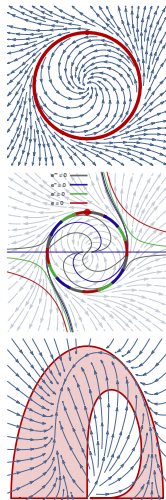
$N$  exists

Semialgebraic Invariants are derived

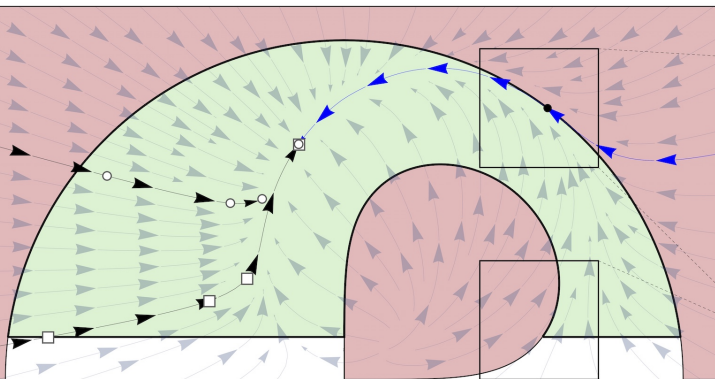
$$\frac{Q \rightarrow \mathbf{e}'^* \succcurlyeq 0 \quad Q \rightarrow \mathbf{e}^{(N)} = \sum_{i=0}^{N-1} g_i \mathbf{e}^{(i)}}{\Gamma \rightarrow [x' = f(x) \& Q]\mathbf{e} \succcurlyeq 0}$$

$$\mathbf{e}'^* \geq 0 \equiv \mathbf{e} \geq 0 \wedge (\mathbf{e} = 0 \rightarrow (\mathbf{e}')^* \geq 0)$$

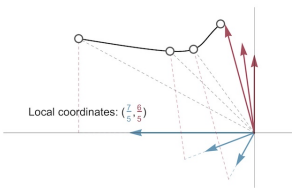
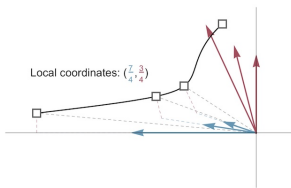
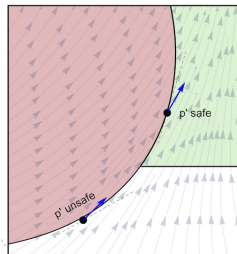
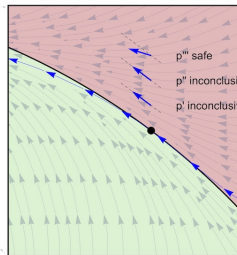
$$\mathbf{e}'^* > 0 \equiv \mathbf{e} > 0 \vee (\mathbf{e} = 0 \wedge (\mathbf{e}')^* > 0)$$



# ODE Axiomatization from Higher Derivatives and Ghosts



Proofs with higher Lie derivatives



Proofs use continuously changing basis to keep invariants at constant local coordinates

Sound and complete ODE invariance proofs

## Unique Solutions

$$\langle x' = f(x) \& Q_1 \wedge Q_2 \rangle P$$

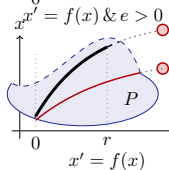
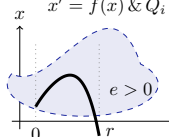
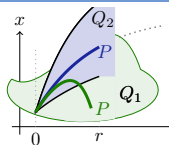
$$\leftrightarrow \langle x' = f(x) \& Q_1 \rangle P \wedge \langle x' = f(x) \& Q_2 \rangle P$$

## Continuous Existence

$$\langle x' = f(x) \& e > 0 \rangle x \neq y \leftrightarrow e > 0$$

## Real Induction

$$[x' = f(x)]P \leftrightarrow \forall y [x' = f(x) \& P \vee x=y] \\ (x=y \rightarrow P \wedge \langle x' = f(x) \& P \rangle x \neq y)$$



## Unique Solutions

$$\langle x' = f(x) \& Q_1 \wedge Q_2 \rangle P$$

$$\leftrightarrow \langle x' = f(x) \& Q_1 \rangle P \wedge \langle x' = f(x) \& Q_2 \rangle P$$

## Continuous Existence

$$\langle x' = f(x) \& e > 0 \rangle x \neq y \leftrightarrow e > 0$$

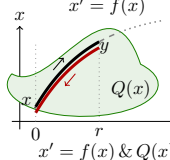
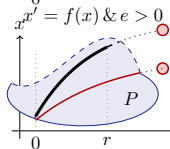
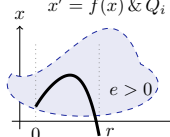
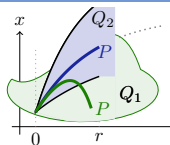
## Real Induction

$$[x' = f(x)] P \leftrightarrow \forall y [x' = f(x) \& P \vee x=y]$$

$$(x=y \rightarrow P \wedge \langle x' = f(x) \& P \rangle x \neq y)$$

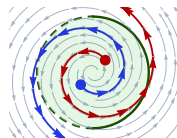
## Differential Adjoint

$$\langle x' = f(x) \& Q(x) \rangle x=y \leftrightarrow \langle y' = -f(y) \& Q(y) \rangle y=x$$



## Real Induction Rule

$$\frac{P \rightarrow \langle x' = f(x) \& P \rangle \circ \quad \neg P \rightarrow \langle x' = -f(x) \& \neg P \rangle \circ}{P \rightarrow [x' = f(x)] P}$$

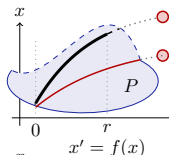


$$\langle x' = f(x) \& P \rangle \circ \equiv \langle y := x \rangle \langle x' = f(x) \& P \vee x = y \rangle x \neq y$$

Local progress to  $P$

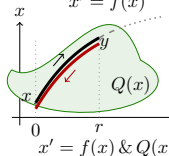
## Real Induction

$$[x' = f(x)] P \leftrightarrow \forall y [x' = f(x) \& P \vee x = y] \\ (x = y \rightarrow P \wedge \langle x' = f(x) \& P \rangle x \neq y)$$



## Differential Adjoint

$$\langle x' = f(x) \& Q(x) \rangle x = y \leftrightarrow \langle y' = -f(y) \& Q(y) \rangle y = x$$





# ODE Axiomatization: Derived Local Progress

## Local Progress Step

$$e > 0 \vee e = 0 \wedge \langle x' = f(x) \& e' \geq 0 \rangle \circ \\ \rightarrow \langle x' = f(x) \& e \geq 0 \rangle \circ$$

## Local Progress $\geq$

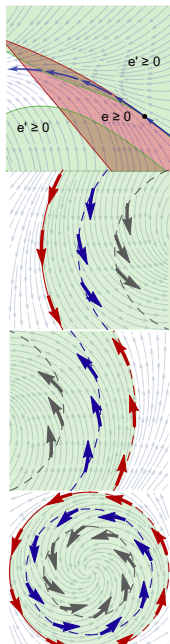
$$e'^* \geq 0 \rightarrow \langle x' = f(x) \& e \geq 0 \rangle \circ$$

## Local Progress $>$

$$e'^* > 0 \rightarrow \langle x' = f(x) \& e > 0 \rangle \circ$$

## Local Progress Semialgebraic

$$\langle x' = f(x) \& P \rangle \circ \leftrightarrow P'^*$$



## Local Progress Step

$$e > 0 \vee e = 0 \wedge \langle x' = f(x) \& e' \geq 0 \rangle \circ \\ \rightarrow \langle x' = f(x) \& e \geq 0 \rangle \circ$$

## Local Progress $\geq$

$$e'^* \geq 0 \rightarrow \langle x' = f(x) \& e \geq 0 \rangle \circ$$

## Local Progress $>$

$$e'^* > 0 \rightarrow \langle x' = f(x) \& e > 0 \rangle \circ$$

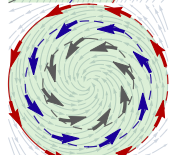
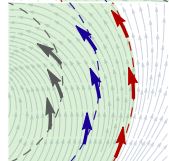
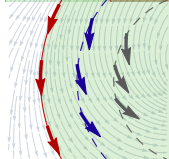
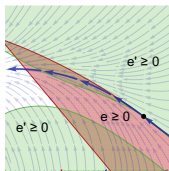
## Local Progress Semialgebraic

$$\langle x' = f(x) \& P \rangle \circ \leftrightarrow P'^*$$

$$e'^* \geq 0 \equiv e \geq 0 \wedge \\ (e = 0 \rightarrow (e')'^* \geq 0)$$

$$e'^* > 0 \equiv e > 0 \vee \\ (e = 0 \wedge (e')'^* > 0)$$

$$(P \wedge Q)'^* \equiv P'^* \wedge Q'^* \\ (P \vee Q)'^* \equiv P'^* \vee Q'^*$$



Theorem (Algebraic Completeness) (LICS'18, JACM'20)

*dL calculus is a sound & complete axiomatization of algebraic invariants of polynomial differential equations. They are decidable with a derived axiom:*

$$(DRI) \quad [x' = f(x) \ \& \ Q]e = 0 \leftrightarrow (Q \rightarrow e'^* = 0) \quad (Q \text{ open})$$

Theorem (Semialgebraic Completeness) (LICS'18, JACM'20)

*dL calculus with RI is a sound & complete axiomatization of semialgebraic invariants of differential equations. They are decidable with derived axiom:*

$$(SAI) \quad \forall x (P \rightarrow [x' = f(x)]P) \leftrightarrow \forall x (P \rightarrow P'^*) \wedge \forall x (\neg P \rightarrow (\neg P)'^{*-})$$

Definable  $e'^*$  is short for *all/significant* Lie derivative w.r.t. ODE

Definable  $e'^{*-}$  is w.r.t. backwards ODE  $x' = -f(x)$ . Also for  $P$ .

## Theorem (Analytic Completeness)

(LICS'18, JACM'20)

dL calculus is a sound & complete axiomatization of analytic invariants of analytic differential equations.

$$(DRI) \quad [x' = f(x) \ \& \ Q]e = 0 \leftrightarrow (Q \rightarrow e'^* = 0) \quad (Q \text{ open})$$

## Theorem (Semianalytic Completeness)

(LICS'18, JACM'20)

dL calculus with RI is a sound & complete axiomatization of semianalytic invariants of differential equations.

$$(SAI) \quad \forall x (P \rightarrow [x' = f(x)]P) \leftrightarrow \forall x (P \rightarrow P'^*) \wedge \forall x (\neg P \rightarrow (\neg P)^{*'--})$$

(S) Smooth function interpretations  $h : \mathbb{R}^k \rightarrow \mathbb{R}$

(P) Partial derivatives of  $h(y_1, \dots, y_k)$  have syntactic term representation  $\frac{\partial h}{\partial y_i}$

(R) Computable differential radicals: compute  $N, g_i$  for  $e^{(N)} = \sum_{i=0}^{N-1} g_i e^{(i)}$

## Definition (Noetherian Function)

$h : H \subseteq \mathbb{R}^k \rightarrow \mathbb{R}$  is *Noetherian function* iff  $h(y) = p(y, h_1(y), \dots, h_r(y))$  for a polynomial  $p$  and *Noetherian chain*  $h_1, \dots, h_r : H \subseteq \mathbb{R}^k \rightarrow \mathbb{R}$ , i.e., real analytic

$$\frac{\partial h_j}{\partial y_i}(y) = q_{ij}(y, h_1(y), \dots, h_r(y)) \text{ for some polynomial } q_{ij} \in \mathbb{R}[y, z]$$

Example:  $\frac{\partial \sin}{\partial y}(y) = \cos(y)$  and  $\frac{\partial \cos}{\partial y}(y) = -\sin(y)$  and  $\frac{\partial \exp}{\partial y}(y) = \exp(y)$

**Theorem** Noetherian functions satisfy SPR conditions.

$\Rightarrow$  Completeness for logic + differential equations with Noetherian functions.

(S) **Smooth** function interpretations  $h : \mathbb{R}^k \rightarrow \mathbb{R}$

(P) **Partial derivatives** of  $h(y_1, \dots, y_k)$  have syntactic term representation  $\frac{\partial h}{\partial y_i}$

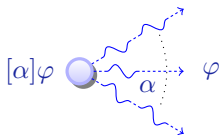
(R) **Computable differential radicals**: compute  $N, g_i$  for  $e^{(N)} = \sum_{i=0}^{N-1} g_i e^{(i)}$



- 1 Differential Dynamic Logic
  - Syntax
  - Axiomatization
  - Relative Completeness / ODE
- 2 Proofs for Differential Equations
  - Differential Invariants / Cuts / Ghosts
- 3 Completeness for Differential Equation Invariants
  - Darboux are Differential Ghosts
  - Derived Differential Radical Invariants
  - Real Induction
  - Derived Local Progress
  - Completeness for Invariants
  - Completeness for Noetherian Functions
- 4 Summary

differential dynamic logic

$$dL = DL + HP$$



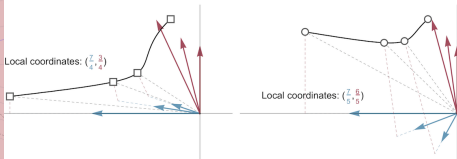
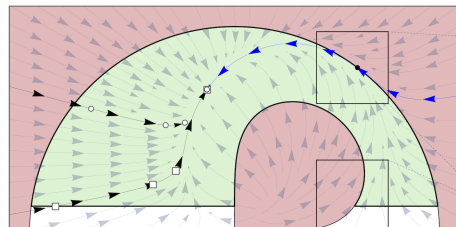
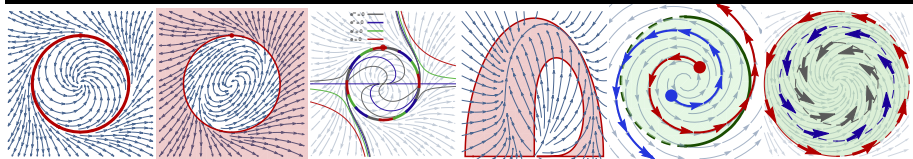
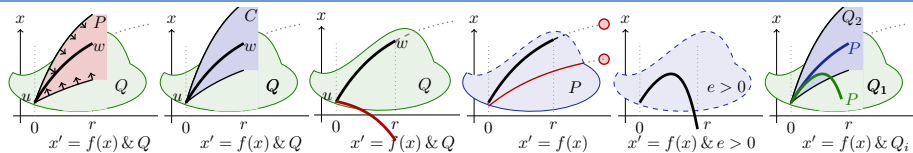
## Properties

- 1 Poincaré: qualitative ODE
- 2 Complete axiomatization
- 3 Algebraic ODE invariants
- 4 Semialgebraic ODE invariants
- 5 Algebraic hybrid systems
- 6 Local ODE progress
- 7 Decide by dL proof/disproof
- 8 Uniform substitution axioms
- 9 Analytic extensions: Noetherian

- |                          |                           |
|--------------------------|---------------------------|
| 1 MVT                    | 1 Differential invariants |
| 2 Prefix                 | 2 Differential cuts       |
| 3 Picard-Lind            | 3 Differential ghosts     |
| 4 $\mathbb{R}$ -complete | 4 Real induction          |
| 5 Existence              | 5 Continuous existence    |
| 6 Uniqueness             | 6 Unique solutions        |

Impressive power of differential ghosts

# Differential Equation Axiomatization vs. Derived Rules





**I Part: Elementary Cyber-Physical Systems**

1. Differential Equations & Domains
2. Choice & Control
3. Safety & Contracts
4. Dynamical Systems & Dynamic Axioms
5. Truth & Proof
6. Control Loops & Invariants
7. Events & Responses
8. Reactions & Delays

**II Part: Differential Equations Analysis**

9. Differential Equations & Differential Invariants
10. Differential Equations & Proofs
11. Ghosts & Differential Ghosts
12. Differential Invariants & Proof Theory

**III Part: Adversarial Cyber-Physical Systems**

- 13-16. Hybrid Systems & Hybrid Games

**IV Part: Comprehensive CPS Correctness**



# Logical Foundations of Cyber-Physical Systems