A Verified Decision Procedure for Univariate Real Arithmetic with the BKR Algorithm

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Problem

- Real arithmetic questions involving the ∃ (exists) and ∀ (for all)
 quantifiers (ranging over the reals) are difficult for computers
- **Quantifier elimination (QE)**: The process of transforming a quantified statement into a *logically equivalent* quantifier-free statement

Examples



Example*

$$\forall x \forall y. ((x^2 + ay^2 \le 1) \Rightarrow (ax^2 - a^2xy + 2 \ge 0))$$

QE
 $(a \ge 0) \text{ and } (a^3 - 8a - 16 \le 0)$

QE is identifying exactly what conditions on a will make the original formula true!

*This example is taken from some of Pablo Parrilo's lecture notes (Lecture 18 of his 2006 course, "Algebraic Techniques and Semidefinite Optimization"). Accessible through his webpage: https://www.mit.edu/~parrilo/index.html

A Miraculous Result

- Algorithms for QE exist (Tarski, 1930)
- Algorithms for QE are complicated



Alfred Tarski

Terminology

- Formulas: Conjunctions and disjunctions of polynomial inequalities and equations (with rational coefficients)
- If a formula in a QE problem involves only one variable, we call it a **univariate** QE problem. Else it is a **multivariate** QE problem
- **Decision problems** are problems where all variables are quantified

Examples, Revisited



Example*

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QE
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A univariate decision problem

A multivariate QE question Not a decision problem

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- Quantified statements arise in a number of applications
 - Geometry proofs
 - Stability analysis
 - Verification of cyber-physical systems (like robots!)



For more information, see: Sturm, T. A Survey of Some Methods for Real Quantifier Elimination, Decision, and Satisfiability and Their Applications. *Math.Comput.Sci.* 11, 483–502 (2017).

- Quantified statements arise in a number of applications
 - Geometry proofs
 - Stability analysis
 - Verification of cyber-physical systems (like robots!)
- Two conclusions
 - We want to know how to do QE
 - We want to be sure that we know how to do QE correctly



• What we want: Formally verified QE algorithms



- What we want: Formally verified QE algorithms
- **Problem:** Dearth of efficient verified QE support
 - CPS theorem prover KeYmaera X outsources QE to unverified software
 - This can introduce bugs



Related Work



	Efficient?	Verified?	Multivariate case builds directly on univariate?
Cohen-Hörmander	X		
Tarski	X	\checkmark	
CAD			X

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CAD			X
BKR & Renegar Potential sweet spot!		X	

BKR and Renegar

- Originally BKR* was a decision procedure
- Renegar** extended BKR to a general-purpose QE algorithm
 - Explains BKR in more detail
 - Fixes an error in BKR's multivariate complexity analysis

*Michael Ben-Or, Dexter Kozen, and John H. Reif. The complexity of elementary algebra and geometry. *J. Comput. Syst. Sci.*, 32(2):251-264, 1986.

**James Renegar. On the computational complexity and geometry of the first-order theory of the reals, part III: quantifier elimination. *J. Symb. Comput.*, 13(3):329-352,1992.

We formally verify^{*} the univariate cases of BKR and Renegar in Isabelle/HOL.



*Available on the Archive of Formal Proofs at: https://www.isa-afp.org/entries/BenOr_Kozen_Reif.html

High-level Context

- ~7000 LOC
 - Algorithm: ~110 LOC
 - Matrix library extensions: ~1800 LOC



High-level Context

- ~7000 LOC
 - Algorithm: ~110 LOC
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- Why Isabelle/HOL?
 - Well-suited to formalizing mathematics
 - Strong math libraries
 - Sledgehammer



Univariate BKR: Bird's Eye View



- Transform the problem:
 - 1. Decision problems to sign determination
 - 2. Sign determination to restricted sign determination
 - 3. To solve restricted sign determination, set up a matrix equation.

The main formalization challenge

Step 1: Decision to Sign Determination

• Solve decision problems by finding the *consistent sign assignments* (*CSAs*) for a set of polynomials (sign determination)

Definition (sign assignment for {g₁, ..., g_n**}).** A mapping σ : {g₁, ..., g_n} \rightarrow {+, -, 0} σ is **consistent** if there is a real x where, for all i, the sign of g_i(x) matches σ (g_i).

Step 1: Decision to Sign Determination

• Solve decision problems by finding the *consistent sign assignments* (*CSAs*) for a set of polynomials (sign determination)

Decision Problem:

$$\exists x. (x^2+1 \ge 0 \land 3x <$$

0)
CSAs: (+

Find all consistent sign assignments for $x^2 + 1$ and 3x

CSAs: (+, -), (+, 0), (+, +)

CSA (+, -) indicates the existence of a point k with $(k^2+1 \ge 0 \land 3k < 0)$

Correctness Results for Step 1



theorem decision_procedure: "($\forall x::real. fml_sem fml x$) \longleftrightarrow decide_universal fml" "($\exists x::real. fml_sem fml x$) \longleftrightarrow decide_existential fml"

Canonical semantics for formulas (defines what it means for a formula to hold at x in the standard way) Our algorithms

Step 2: Restricted Sign Determination

• Restrict sign determination to finding all CSAs for a set of polynomials $\{q_1, ..., q_n\}$ at the roots of an auxiliary nonzero polynomial p



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Restrict sign determination to finding all CSAs for a set of polynomials
 {q₁,..., q_n} at the roots of an auxiliary nonzero polynomial p



Correctness Results for Step 2



definition roots :: "real poly \Rightarrow real set" where "roots $p = \{x. \text{ poly } p \ x = 0\}$ " definition consistent_signs_at_roots :: "real poly \Rightarrow real poly list \Rightarrow rat list set" where "consistent_signs_at_roots $p \ qs = (sgn_vec \ qs)$ ' (roots p)"

Plug in the roots to the q_i's, take the resulting signs

Solve for the roots of a polynomial

Correctness Results for Step 2



definition roots :: "real poly \Rightarrow real set" where "roots $p = \{x. \text{ poly } p \mid x = 0\}$ "

definition consistent_signs_at_roots :: "real poly \Rightarrow real poly list \Rightarrow rat list set" where "consistent_signs_at_roots p qs = (sgn_vec qs) ' (roots p)"

theorem find_consistent_signs_at_roots: assumes "p \neq 0" assumes " $\land q. q \in set qs \implies coprime p q$ " shows "set (find_consistent_signs_at_roots p qs) = consistent_signs_at_roots p qs"

our (constructive) algorithm

the nonconstructive definition

- Stores all relevant information for sign determination
- Idea dates back to Tarski; similarities to Cohen and Mahboubi's formalization*
- But BKR does it efficiently

*Cyril Cohen and Assia Mahboubi. Formal proofs in real algebraic geometry: from ordered fields to quantifier elimination. Log. Methods Comput. Sci., 8(1), 2012. doi:10.2168/ LMCS-8(1:2)2012.



Alfred Tarski



Find sign assignments to $q_1, ..., q_n$ at the roots of p BKR builds its matrix equation (ME) inductively



After each combination, remove all inconsistent sign assignments (reduction step)



Reflections on Formalizing the Matrix Equation

- Inductive construction, inductive proof!
 - It took some work to identify the right inductive invariant
 - The reduction step poses the biggest challenge
- The reduction step requires extra proofs

*Wenda Li. The Sturm-Tarski theorem. Archive of Formal Proofs, September 2014. https: //isa-afp.org/entries/Sturm_Tarski.html, Formal proof development.

Reflections on Formalizing the Matrix Equation

- Isabelle/HOL has well-developed libraries
 - The Sturm-Tarski theorem is already formalized* (the key computational tool for the matrix equation)
 - A number of linear algebra libraries are available

*Wenda Li. The Sturm-Tarski theorem. Archive of Formal Proofs, September 2014. https: //isa-afp.org/entries/Sturm_Tarski.html, Formal proof development.

Extending the Matrix Libraries

- We build on a matrix library by Thiemann and Yamada*
- Our additions (~1800 LOC):
 - A computational notion of the Kronecker product
 - An algorithm to extract a basis from the rows of a matrix
 - Involved proving that row rank equals column rank

Code Export and Experiments

- We export our formally verified algorithm to SML for experimentation
- Compare to:
 - A naive (unverified) version of Tarski's algorithm
 - Li, Passmore, and Paulson*

*Wenda Li, Grant Olney Passmore, and Lawrence C. Paulson. Deciding univariate polynomial problems using untrusted certificates in Isabelle/HOL. J. Autom. Reason., 62(1):69–91, 2019.

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- Compare to:
 - A naive (unverified) version of Tarski's algorithm
 - Li, Passmore, and Paulson*
- Li et. al is faster:
 - CAD is generally faster than BKR
 - Their procedure is highly optimized
 - They use Mathematica as an untrusted oracle



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*Compiled with mlton *Run on a laptop *Dashes indicate timeout *Times in seconds

	Formula	#Poly	N(p,q) (Naive)	N(p,q) (BKR)	Time (Naive)	Time (BKR)	Time ([18])	K
Benchmarks from [18]	ex1 ex2 ex3 ex4 ex5 ex6 ex7	4 (12) 5 (6) 4 (22) 5 (3) 8 (3) 22 (9) 10 (12)	20 576 112 112 576 50331648 6144	31 180 120 95 219	0.003 5.780 1794.843 0.461 28.608	0.006 0.442 1865.313 0.261 8.333	3.020 3.407 3.580 3.828 3.806 6.187	3s startup time for Mathematica
ſ	$ex1 \land 2$ $ex1 \land 2 \land 4$ $ex1 \land 2 \land 5$	9 (12) 13 (12) 16 (12)	2816 28672 131072	298 555 826	317.432	3.027 51.347 436.575	3.033 3.848 3.711	

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Formula	#Poly	N(p,q) (Naive)	N(p,q) (BKR)	Time (Naive)	Time (BKR)	Time ([18])
ex1	4 (12)	20	31	0.003	0.006	3.020
ex2	5 (6)	576	180	5.780	0.442	3.407
ex3	4 (22)	112	120	1794.843	1865.313	3.580
ex4	5 (3)	112	95	0.461	0.261	3.828
ex5	8 (3)	576	219	28.608	8.333	3.806
ex6	22 (9)	50331648	-	-	-	6.187
ex7	10 (12)	6144	-	-	-	-
$ex1 \wedge 2$	9 (12)	2816	298	317.432	3.027	3.033
$ex1 \wedge 2 \wedge 4$	13 (12)	28672	555	-	51.347	3.848
$ex1 \wedge 2 \wedge 5$	16 (12)	131072	826	-	436.575	3.711

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Future Work and Conclusion

Future Work

- Optimizing univariate BKR
 - Add parallelism
 - Optimize Tarski queries
- Formally verified complexity analysis (ambitious!)
- Formalizing multivariate BKR

Conclusion

• We have formally verified the univariate case of BKR's QE algorithm

- BKR hits a potential **sweet spot** in between practicality and ease of verification
- Contributes to Isabelle/HOL's matrix libraries
- Export code to SML for faster runtime
- Multivariate BKR is ongoing work

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