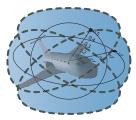
15-819/18-879: Logical Analysis of Hybrid Systems28: Complete Axiomatization of Differential Dynamic Logic

André Platzer

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1) Verification Calculus for Differential Dynamic Logic d ${\cal L}$

Compositionality Motives

2 Soundness

3 Completeness

- Incompleteness
- Completeness
- Expressibility and Rendition of Hybrid Programs
- Relative Completeness of First-Order Assertions
- Relative Completeness of Differential Logic Calculus



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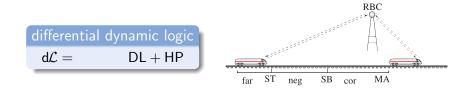
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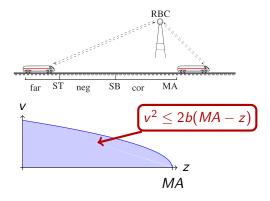
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${\mathcal R}$ d ${\mathcal L}$ Motives: The Logic of Hybrid Systems

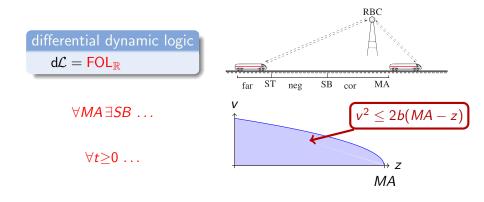


\mathcal{R} d \mathcal{L} Motives: Regions in First-order Logic

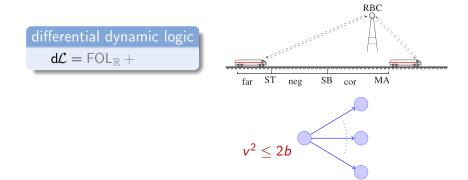




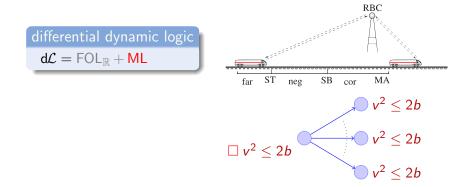
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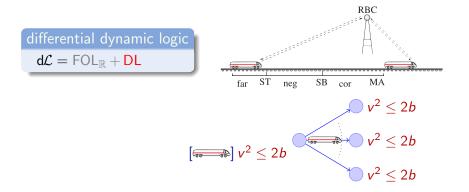
\mathcal{R} d \mathcal{L} Motives: State Transitions in Dynamic Logic



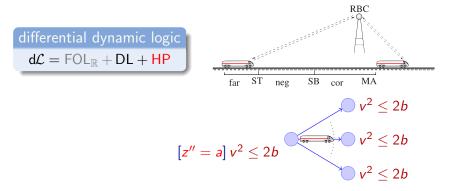
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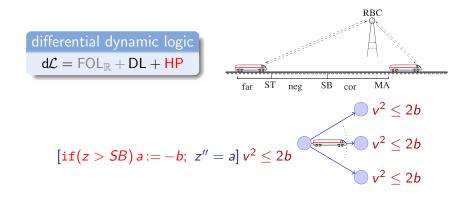
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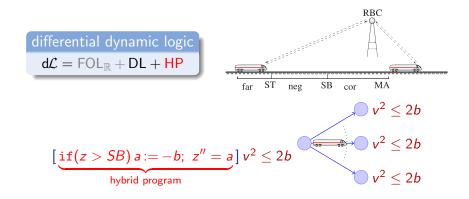
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ℜ Verification Calculus for Differential Dynamic Logic Propositional Rules

10 propositional rules

$\frac{\vdash \phi}{\neg \phi \vdash}$	$\frac{\phi,\psi\vdash}{\phi\wedge\psi\vdash}$	$\frac{\phi \vdash \psi \vdash}{\phi \lor \psi \vdash}$	$\frac{\vdash \phi \ \phi \vdash}{\vdash}$
$\frac{\phi \vdash}{\vdash \neg \phi}$	$\frac{\vdash \phi \vdash \psi}{\vdash \phi \land \psi}$	$\frac{\vdash \phi, \psi}{\vdash \phi \lor \psi}$	
$\frac{\phi \vdash \psi}{\vdash \phi \rightarrow \psi}$	$\frac{\vdash \phi \psi \vdash}{\phi \rightarrow \psi \vdash}$	$\overline{\phi\vdash\phi}$	

ℜ Verification Calculus for Differential Dynamic Logic Dynamic Rules

$$\frac{\langle \alpha \rangle \langle \beta \rangle \phi}{\langle \alpha; \beta \rangle \phi} \qquad \qquad \frac{\phi \lor \langle \alpha \rangle \langle \alpha^* \rangle \phi}{\langle \alpha^* \rangle \phi} \qquad \frac{\phi_{x_1}^{\theta_1} \dots \theta_n}{\langle x_1 := \theta_1, \dots, x_n := \theta_n \rangle \phi}$$

$$\frac{[\alpha][\beta]\phi}{[\alpha;\beta]\phi} \qquad \qquad \frac{\phi \wedge [\alpha][\alpha^*]\phi}{[\alpha^*]\phi} \qquad \frac{\langle x_1 := \theta_1, \dots, x_n := \theta_n \rangle \phi}{[x_1 := \theta_1, \dots, x_n := \theta_n]\phi}$$

$$\frac{\langle \alpha \rangle \phi \lor \langle \beta \rangle \phi}{\langle \alpha \cup \beta \rangle \phi} \quad \frac{\chi \land \psi}{\langle ?\chi \rangle \psi} \quad \frac{\exists t \ge 0 \left((\forall 0 \le \tilde{t} \le t \langle \mathcal{S}(\tilde{t}) \rangle \chi) \land \langle \mathcal{S}(t) \rangle \phi \right)}{\langle x_1' = \theta_1, \dots, x_n' = \theta_n \land \chi \rangle \phi}$$

$$\frac{[\alpha]\phi \wedge [\beta]\phi}{[\alpha \cup \beta]\phi} \qquad \frac{\chi \to \psi}{[?\chi]\psi} \qquad \qquad \frac{\forall t \ge 0 \left((\forall 0 \le \tilde{t} \le t \langle \mathcal{S}(\tilde{t}) \rangle \chi) \to \langle \mathcal{S}(t) \rangle \phi \right)}{[x_1' = \theta_1, \dots, x_n' = \theta_n \wedge \chi]\phi}$$

✤ Verification Calculus for Differential Dynamic Logic First-Order Rules

$$\frac{\vdash \phi(s(X_1,\ldots,X_n))}{\vdash \forall x \, \phi(x)}$$

$$\frac{\vdash \phi(X)}{\vdash \exists x \, \phi(x)}$$

$$\frac{\phi(s(X_1,\ldots,X_n))\vdash}{\exists x\,\phi(x)\vdash}$$

s new, $\{X_1, \ldots, X_n\} = FV(\exists x \phi(x))$

$$\frac{\phi(X) \vdash}{\forall x \, \phi(x) \vdash}$$

X new variable

$$\frac{\vdash \mathsf{QE}(\forall X \ (\Phi(X) \vdash \Psi(X)))}{\Phi(s(X_1, \dots, X_n)) \vdash \Psi(s(X_1, \dots, X_n))} \qquad \frac{\vdash \mathsf{QE}(\exists X \ \bigwedge_i (\Phi_i \vdash \Psi_i))}{\Phi_1 \vdash \Psi_1 \ \dots \ \Phi_n \vdash \Psi_n}$$

X new variable X only in branches $\Phi_i \vdash \Psi_i$

QE needs to be defined in premiss

André Platzer (CMU)

LAHS/28: Completeness of Differential Dynamic Logic

$$\frac{\vdash \forall^{\alpha}(\phi \to \psi)}{[\alpha]\phi \vdash [\alpha]\psi}$$

$$\frac{\vdash \forall^{\alpha} (\phi \to \psi)}{\langle \alpha \rangle \phi \vdash \langle \alpha \rangle \psi}$$

$$\frac{\vdash \forall^{\alpha} (\phi \to [\alpha] \phi)}{\phi \vdash [\alpha^*] \phi}$$

$$\frac{\vdash \forall^{\alpha} \forall v > 0 \left(\varphi(v) \to \langle \alpha \rangle \varphi(v-1)\right)}{\exists v \, \varphi(v) \vdash \langle \alpha^* \rangle \exists v \leq 0 \, \varphi(v)}$$



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dL calculus is sound, i.e.,

$$\vdash \phi \implies \vdash \phi$$



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- Free variables & Skolemization



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Can we prove all valid formulas of $d\mathcal{L}$?

$$\vDash \phi \implies \vdash \phi?$$

Theorem (Incompleteness)

Both the discrete fragment and the continuous fragment of $d\mathcal{L}$ are not effectively axiomatisable, i.e., they have no sound and complete effective calculus, because natural numbers are definable in both fragments.

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Theorem (Gödels's Incompleteness'31)

First-order logic with (non-linear) arithmetic of natural numbers has no sound and complete effective calculus.

Proof (Incompleteness)

Discrete fragment:

$$\langle (x := x + 1)^* \rangle \ x = n$$

+1 +1 +1 +1 +1 +1

Proof (Incompleteness)

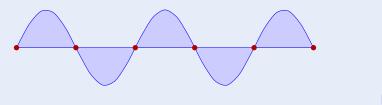
Discrete fragment:

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$$\xrightarrow{+1} \xrightarrow{+1} \xrightarrow{+1} \xrightarrow{+1} \xrightarrow{+1} \xrightarrow{+1}$$

Continuous fragment:

$$\langle s'' = -s, \tau' = 1 \rangle (s = 0 \land \tau = n) \longrightarrow s = \sin s$$



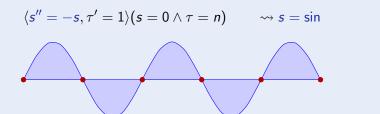
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What's missing in characterization?

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What's missing in characterization? $s \neq 0 \lor s'(0) \neq 0$

Relativity

 $\mathsf{Cook}, \mathsf{Harel:} \quad \mathsf{discrete-DL}/\mathsf{data}_{\mathbb{N}} \qquad \qquad \mathsf{hybrid-d}\mathcal{L}/\mathsf{data}_{\mathbb{R}} ~ \ref{eq:loss}$









\mathcal{R} Sources of Incompleteness



\mathcal{R} Relative Completeness



ℜ Relative Completeness



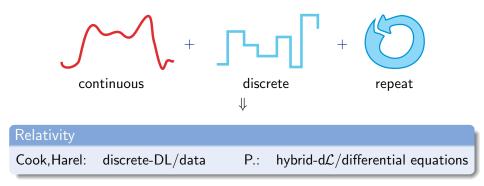
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d*L* calculus is a sound & complete axiomatisation of hybrid systems relative to differential equations.



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\mathcal{R} First-Order Logic of Differential Equations FOD

Definition (First-Order Logic of Differential Equations)

$$FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$$

FOD $\phi ::= \theta_1 \ge \theta_2 \mid \neg \phi \mid \phi_1 \land \phi_2 \mid \forall x \phi \mid \exists x \phi \mid [x'_1 = \theta_1, \dots, x'_n = \theta_n]\phi$

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both will do

Theorem (Relative Completeness)

d*L* calculus is complete relative to first-order logic of differential equations.

 $\models \phi \quad iff \quad Taut_{FOD} \vdash \phi$

where $FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$

Proof Outline 15p

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▶ Proof Outline 15p

Corollary (Proof-theoretical Alignment)

verification of hybrid systems = verification of dynamical systems!

$$\models \phi \quad \text{iff} \quad Taut_{\text{FOD}} \vdash \phi$$

where
$$FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$$

- ${\small \textcircled{0}}$ Strong enough invariants and variants expressible in d ${\small \mathcal{L}}$
- $\textcircled{0} d\mathcal{L} \text{ expressible in FOD}$
- valid dL formulas dL-derivable from corresponding FOD axioms
- Inite FOD formula characterising unbounded hybrid repetition
- FOD characterises R-Gödel encoding
- First-order expressible & program rendition: for each φ there is F ∈ FOD ⊨ φ ↔ F
- Propositionally & first-order complete
- **③** Relative complete for first-order safety $F \rightarrow [\alpha]G$
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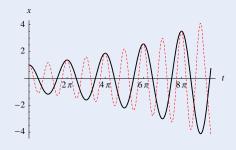
\mathcal{R} Relative Completeness Proof

where
$$FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$$

▲ Return

Proof (\mathbb{R} -Gödel encoding).

FOD characterises constructive bijection $\mathbb{R} \to \mathbb{R}^2$

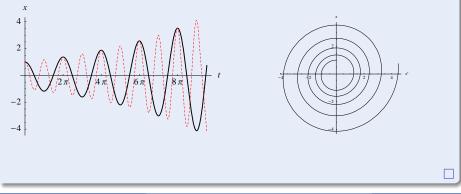


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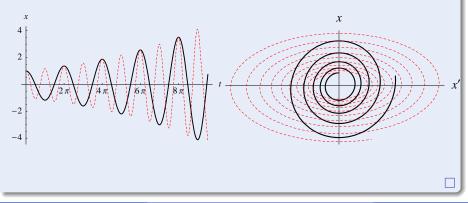
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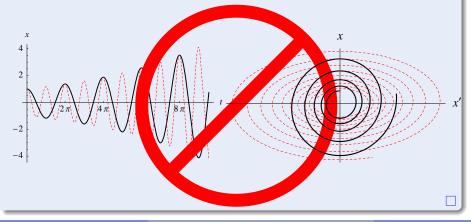


LAHS/28: Completeness of Differential Dynamic Logic

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FOD characterises constructive bijection $\mathbb{R} \to \mathbb{R}^2$ not differentiable!



LAHS/28: Completeness of Differential Dynamic Logic

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$$\sum_{i=0}^{\infty} \frac{a_i}{2^i} = a_0.a_1a_2...$$

$$\sum_{i=0}^{\infty} \frac{b_i}{2^i} = b_0.b_1b_2...$$

$$\sum_{i=0}^{\infty} \left(\frac{a_i}{2^{2i-1}} + \frac{b_i}{2^{2i}}\right) = a_0b_0.a_1b_1a_2b_2...$$

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$$Z, n, j, z) \leftrightarrow \forall i : \mathbb{Z} \text{ digit}(z, i) = \text{digit}(Z, n(i-1)+j) \land n > 0 \land n, j \in \mathbb{N}$$

$$\lim_{i \neq i} \sum_{j=1}^{\infty} \frac{b_j}{2^{j-1}} = \lim_{i \neq j \neq i} \sum_{j=1}^{\infty} \frac{b$$

$$\begin{aligned} \text{digit}(a, i) &= \text{intpart}(2 \operatorname{frac}(2^{i-a})) \\ \text{intpart}(a) &= a - \operatorname{frac}(a) \\ \text{frac}(a) &= z \leftrightarrow \exists i : \mathbb{Z} \ z = a - i \land -1 < z \land z < 1 \land az \ge 0 \end{aligned}$$
 "keep sign"

at(2

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 $2^{i} = z \leftrightarrow i \ge 0 \land \langle x := 1; t := 0; x' = x \ln 2, t' = 1 \rangle (t = i \land x = z) \\ \lor i < 0 \land \langle x := 1; t := 0; x' = -x \ln 2, t' = -1 \rangle (t = i \land x = z) \\ \ln 2 = z \leftrightarrow \langle x := 1; t := 0; x' = x, t' = 1 \rangle (x = 2 \land t = z)$

$$\vDash \phi \quad \text{iff} \quad Taut_{\mathsf{FOD}} \vdash \phi$$

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- Inite FOD formula characterising unbounded hybrid repetition
- **§** FOD characterises \mathbb{R} -Gödel encoding
- First-order expressible & program rendition: for each φ there is F ∈ FOD ⊨ φ ↔ F
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- **2** Relative complete for first-order liveness $F \rightarrow \langle \alpha \rangle G$

$$\vDash \phi \quad \text{iff} \quad Taut_{\mathsf{FOD}} \vdash \phi$$

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$$FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$$

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Lemma (Program rendition)

For every HP α with variables among $\vec{x} = x_1, \ldots, x_k$ there is a FOD-formula $S_{\alpha}(\vec{x}, \vec{v})$ with variables among the 2k distinct variables $\vec{x} = x_1, \ldots, x_k$ and $\vec{v} = v_1, \ldots, v_k$ such that

$$\models \mathcal{S}_{\alpha}(\vec{x},\vec{v}) \leftrightarrow \langle \alpha \rangle \vec{x} = \vec{v}$$

or, equivalently, for every I, η , v,

$$I, \eta, \mathsf{v} \models \mathcal{S}_{\alpha}(\vec{x}, \vec{v}) \text{ iff } (\mathsf{v}, \mathsf{v}[\vec{x} \mapsto \llbracket \vec{v} \rrbracket_{I, \mathsf{v}, \eta}]) \in \rho_{I, \eta}(\alpha) \ .$$

\cancel{R} Program Rendition Proof

Proof.

$$\begin{split} \mathcal{S}_{x_{1}:=\theta_{1},..,x_{k}:=\theta_{k}}(\vec{x},\vec{v}) &\equiv \bigwedge_{i=1}^{k} (v_{i}=\theta_{i}) \\ \mathcal{S}_{x_{1}'=\theta_{1},..,x_{k}'=\theta_{k}}(\vec{x},\vec{v}) &\equiv \langle x_{1}'=\theta_{1},..,x_{k}'=\theta_{k} \rangle \vec{v} = \vec{x} \\ \mathcal{S}_{x_{1}'=\theta_{1},..,x_{k}'=\theta_{k} \wedge \chi}(\vec{x},\vec{v}) &\equiv \langle t:=0;x_{1}'=\theta_{1},..,x_{k}'=\theta_{k},t'=1 \rangle (\vec{v}=\vec{x}) \\ &\wedge [x_{1}'=-\theta_{1},..,x_{k}'=-\theta_{k},t'=-1](t \geq 0 \rightarrow \chi) \\ \mathcal{S}_{?\chi}(\vec{x},\vec{v}) &\equiv \vec{v}=\vec{x} \wedge \chi \\ \mathcal{S}_{\beta \cup \gamma}(\vec{x},\vec{v}) &\equiv \mathcal{S}_{\beta}(\vec{x},\vec{v}) \lor \mathcal{S}_{\gamma}(\vec{x},\vec{v}) \\ \mathcal{S}_{\beta;\gamma}(\vec{x},\vec{v}) &\equiv \exists \vec{z} (\mathcal{S}_{\beta}(\vec{x},\vec{z}) \wedge \mathcal{S}_{\gamma}(\vec{z},\vec{v})) \\ \mathcal{S}_{\beta^{*}}(\vec{x},\vec{v}) &\equiv \exists Z \exists n : \mathbb{N} (Z_{1}^{(n)}=\vec{x} \wedge Z_{n}^{(n)}=\vec{v} \\ &\wedge \forall i : \mathbb{N} (1 \leq i < n \rightarrow \mathcal{S}_{\beta}(Z_{i}^{(n)}, Z_{i+1}^{(n)}))) \end{split}$$

\mathcal{R} Program Rendition Proof

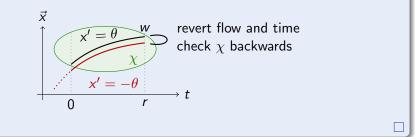
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$$\begin{split} \mathcal{S}_{x_1'=\theta_1,\dots,x_k'=\theta_k\wedge\chi}(\vec{x},\vec{v}) &\equiv \langle t := 0; x_1'=\theta_1,\dots,x_k'=\theta_k, t'=1 \rangle \big(\vec{v}=\vec{x} \\ & \wedge [x_1'=-\theta_1,\dots,x_k'=-\theta_k,t'=-1] (t \ge 0 \to \chi) \end{split}$$



Lemma (Expressibility)

d \mathcal{L} expressible in FOD: for all d \mathcal{L} formulas $\phi \in \mathsf{FmI}$ there is a FOD-formula $\phi^{\#} \in \mathsf{FmI}_{FOD}$ that is equivalent, i.e., $\vDash \phi \leftrightarrow \phi^{\#}$.

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$$\models \quad \langle \alpha \rangle \psi \leftrightarrow \exists \vec{\mathbf{v}} \left(\mathcal{S}_{\alpha}(\vec{\mathbf{x}}, \vec{\mathbf{v}}) \land \psi^{\#\vec{\mathbf{v}}}_{\vec{\mathbf{x}}} \right)$$

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The proof follows an induction on the structure of formula ϕ .

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$$\vdash \langle \alpha \rangle \psi \leftrightarrow \exists \vec{v} \left(S_{\alpha}(\vec{x}, \vec{v}) \land \psi^{\#}_{\vec{x}}^{\nu} \right) \\ \vdash [\alpha] \psi \leftrightarrow \forall \vec{v} \left(S_{\alpha}(\vec{x}, \vec{v}) \rightarrow \psi^{\#}_{\vec{x}}^{\vec{v}} \right)$$

Lemma (Derivability of sequents)

 $\vdash_{\mathcal{D}} \phi \rightarrow \psi$ iff the sequent $\phi \vdash \psi$ is derivable from \mathcal{D} , denoted by $\phi \vdash_{\mathcal{D}} \psi$.

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• The converse direction is by an application of $\rightarrow r$.

\mathcal{R} Generalization

Lemma (Generalization)

If $\vdash_{\mathcal{D}} \phi$ is provable without free logical variables, then so are $\vdash_{\mathcal{D}} \forall x \phi$ and $\vdash_{\mathcal{D}} \langle x_1 := \theta_1, \dots, x_n := \theta_n \rangle \phi$.

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Proof Sketch.

 Second part: Induction on the structure of proofs with inductive jump prefix transformation (1page proof).

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- Using $\forall r$, continue derivation to a proof of $\forall X \langle x := X \rangle \phi$, which we abbreviate as $\forall x \phi$.

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- Using ∀r, continue derivation to a proof of ∀X ⟨x := X⟩φ, which we abbreviate as ∀x φ.
- Rule ∀r is applicable for Skolem constant *s* as no free logical variables occur in the proof.

Proposition (Relative completeness of first-order safety)

For every $\alpha \in HP(\Sigma)$ and each $F, G \in Fml_{FOL}$

 $\vDash F \to [\alpha]G \text{ implies } \vdash_{\mathcal{D}} F \to [\alpha]G \quad (\text{thus } F \vdash_{\mathcal{D}} [\alpha]G)$

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- Thus, we can derive $F \rightarrow [\alpha]G$ by applying the respective rule.
- $\models F \rightarrow [x'_1 = f(x_1)_1, \dots, x'_n = f(x_n)_n]G$ is a FOD-formula and hence derivable as a \mathcal{D} axiom.

• \models *F* \rightarrow [β ; γ]*G*, which implies \models *F* \rightarrow [β][γ]*G*.

- \models $F \rightarrow [\beta; \gamma]G$, which implies \models $F \rightarrow [\beta][\gamma]G$.
- By Expr, there is a FOD-formula $G^{\#}$ such that $\vDash G^{\#} \leftrightarrow [\gamma]G$.

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- Combining propositionally by cut with $[\beta]G^{\#}$, derive $F \vdash_{\mathcal{D}} [\beta][\gamma]G$,
- from which composition [;] yields $F \vdash_{\mathcal{D}} [\beta; \gamma] G$.

Proof (α of the form β^*)

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- Combining propositionally by cut with $[\beta^*]\phi$ and ϕ yields $F \vdash_{\mathcal{D}} [\beta^*]G$.

Proposition (Relative completeness of first-order liveness)

For every $\alpha \in HP(\Sigma)$ and each $F, G \in Fml_{FOL}$

 $\vDash F \to \langle \alpha \rangle G \text{ implies } \vdash_{\mathcal{D}} F \to \langle \alpha \rangle G \quad (\text{thus } F \vdash_{\mathcal{D}} \langle \alpha \rangle G) \ .$

\checkmark Relative Completeness of First-Order Liveness Assertions

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 $\exists \vec{v} \, \exists Z \, \big(Z_1^{(n)} = \vec{x} \wedge Z_n^{(n)} = \vec{v} \wedge \forall i : \mathbb{N} \, \left(1 \leq i < n \rightarrow \mathcal{S}_\beta(Z_i^{(n)}, Z_{i+1}^{(n)}) \right) \wedge G_{\vec{x}}^{\vec{v}} \big)$

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Theorem (Relative Completeness)

d*L* calculus is complete relative to first-order logic of differential equations.

 $\models \phi$ iff Taut_{FOD} $\vdash \phi$

where
$$FOD = FOL_{\mathbb{R}} + [x'_1 = \theta_1, \dots, x'_n = \theta_n]F$$

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- Express subformulas φ_i equivalently in FOD and resolve these first-order safety or liveness assertions by previous propositions.
- Finally, prove that the original d \mathcal{L} formula can be re-derived from the subproofs.

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- For a simple and uniform proof, assume quantifiers to be abbreviations for modal formulas:

$$\exists x \phi \equiv \langle x' = 1 \rangle \phi \lor \langle x' = -1 \rangle \phi$$

$$\forall x \phi \equiv [x' = 1] \phi \land [x' = -1] \phi$$

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- ϕ disjunction, hence (otherwise use associativity and commutativity):

$$\begin{array}{rcl}
\phi_1 & \lor & [\alpha]\phi_2 \\
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• $\models \phi_1 \leftrightarrow \phi_1^{\#}$ implies $\models \neg \phi_1 \rightarrow \neg \phi_1^{\#}$, which is derivable by IH, because $|\phi_1| < |\phi|$. By lemma, $\neg \phi_1 \vdash_{\mathcal{D}} \neg \phi_1^{\#}$, which we combine with (1) by a cut with $\neg \phi_1^{\#}$ to

$$\neg \phi_1 \vdash_{\mathcal{D}} \langle\!\!\!\langle \alpha \rangle\!\!\!\rangle \phi_2^\# \quad . \tag{2}$$

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- Conclude $\vdash_{\mathcal{D}} \phi_1 \vee \langle\!\![\alpha]\!\!\rangle \phi_2$ with a cut.

Theorem (Relative Completeness)

d*L* calculus is a sound & complete axiomatisation of hybrid systems relative to differential equations.

