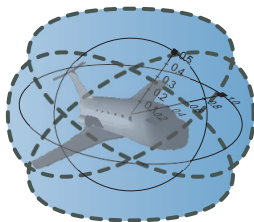


# Differential Game Logic

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ACM TOCL 2015





- 1 CPS Game Motivation
- 2 Differential Game Logic
  - Syntax
  - Example: Robot Dance
  - Differential Hybrid Games
  - Denotational Semantics
  - Determinacy
- 3 Axiomatization
  - Axiomatics
  - Soundness and Completeness
  - Separating Axioms
- 4 Expressiveness
- 5 Summary



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Which control decisions are safe for aircraft collision avoidance?

## Cyber-Physical Systems

CPSs combine cyber capabilities with physical capabilities to solve problems that neither part could solve alone.

Can you trust a computer to control physics?

# Can you trust a computer to control physics?

- 1 Depends on how it has been programmed
- 2 And on what will happen if it malfunctions

## Rationale

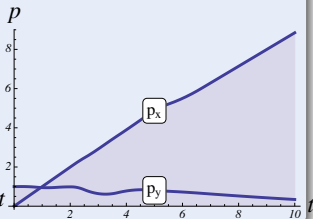
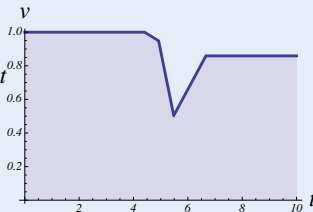
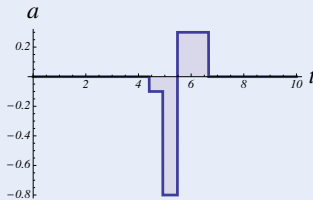
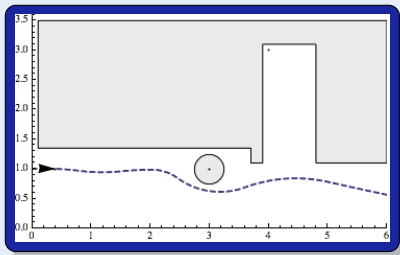
- 1 Safety guarantees require analytic foundations.
- 2 A common foundational core helps all application domains.
- 3 Foundations revolutionized digital computer science & our society.
- 4 Need even stronger foundations when software reaches out into our physical world.

CPSs deserve proofs as safety evidence!

## Challenge (Hybrid Systems)

Fixed rule describing state evolution with both

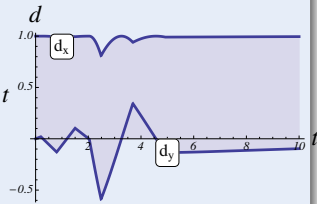
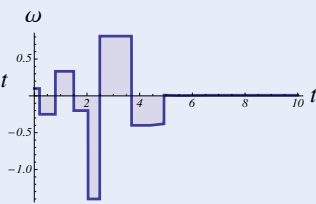
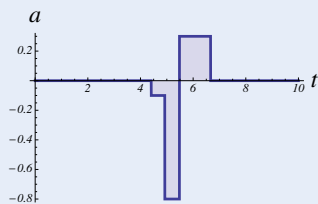
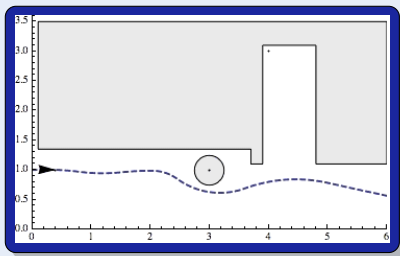
- Discrete dynamics (control decisions)
- Continuous dynamics (differential equations)



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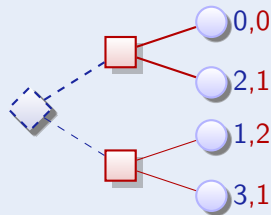




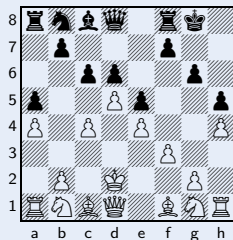
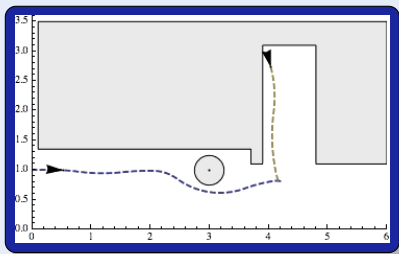
## Challenge (Games)

Game rules describing play evolution with both

- Angelic choices (player  $\diamond$  Angel)
- Demonic choices (player  $\square$  Demon)



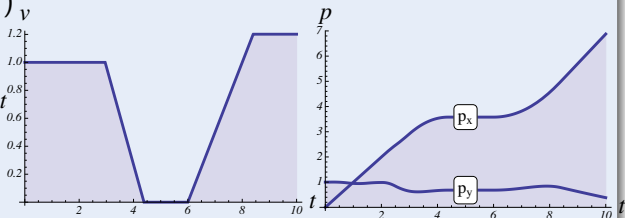
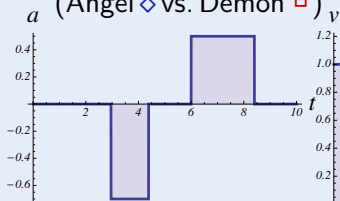
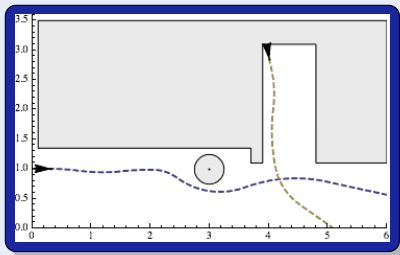
$\diamond \backslash \square$	Tr	Pl
Trash	1,2	0,0
Plant	0,0	2,1



## Challenge (Hybrid Games)

Game rules describing play evolution with

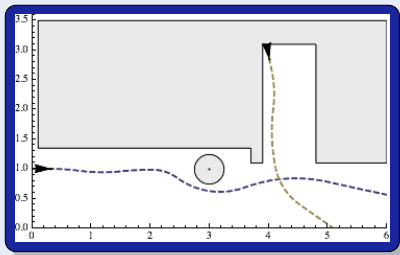
- Discrete dynamics (control decisions)
- Continuous dynamics (differential equations)
- Adversarial dynamics (Angel  $\diamond$  vs. Demon  $\square$ )



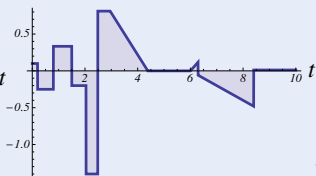
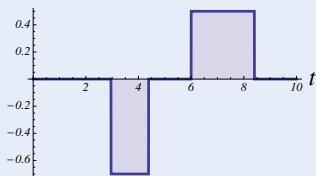
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Game rules describing play evolution with

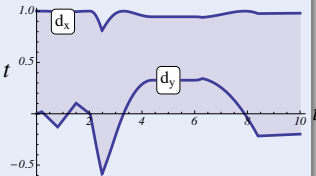
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$a$  (Angel  $\diamond$  vs. Demon  $\square$ )  $\omega$



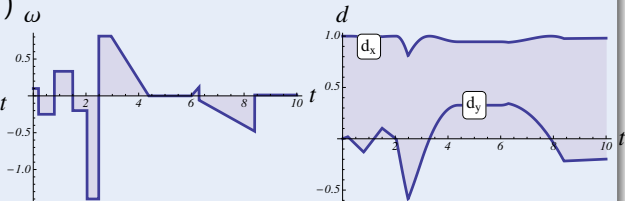
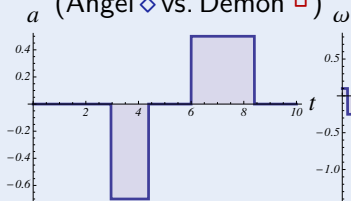
$d$



## Challenge (Hybrid Games)

Game rules describing play evolution with

- Discrete dynamics (control decisions)
- Continuous dynamics (differential equations)
- Adversarial dynamics (Angel  $\diamond$  vs. Demon  $\square$ )





## Logical foundations for hybrid games

- 1 Compositional programming language for hybrid games
- 2 Compositional logic and proof calculus for winning strategy existence
- 3 Hybrid games determined
- 4 Winning region computations terminate after  $\geq \omega_1^{\text{CK}}$  iterations
- 5 Separate truth ( $\exists$  winning strategy) vs. proof (winning certificate) vs. proof search (automatic construction)
- 6 Sound & relatively complete
- 7 Expressiveness
- 8 Fragments successful in applications
- 9 Generalizations in logic enable more applications



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## Definition (Hybrid game $\alpha$ )

$x := f(x) \mid ?Q \mid x' = f(x) \mid \alpha \cup \beta \mid \alpha; \beta \mid \alpha^* \mid \alpha^d$

## Definition (dGL Formula $P$ )

$p(e_1, \dots, e_n) \mid e \geq \tilde{e} \mid \neg P \mid P \wedge Q \mid \forall x P \mid \exists x P \mid \langle \alpha \rangle P \mid [\alpha] P$

Discrete  
Assign

Test  
Game

Differential  
Equation

Choice  
Game

Seq.  
Game

Repeat  
Game

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All  
Reals

Some  
Reals



Discrete  
Assign

Test  
Game

Differential  
Equation

Choice  
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Seq.  
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Repeat  
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Dual  
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Angel  
Wins

Discrete  
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“Angel has Wings  $\langle \alpha \rangle$ ”

All  
Reals

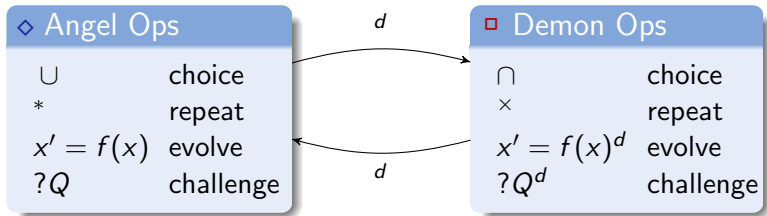
Some  
Reals

Angel  
Wins

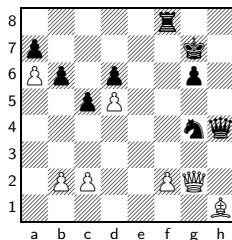
Demon  
Wins



# Game Operators

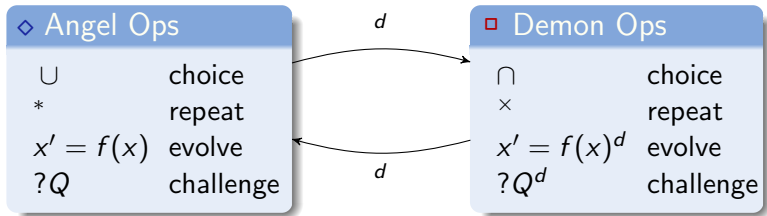


Duality operator  $d$  passes control between players

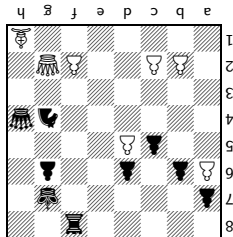


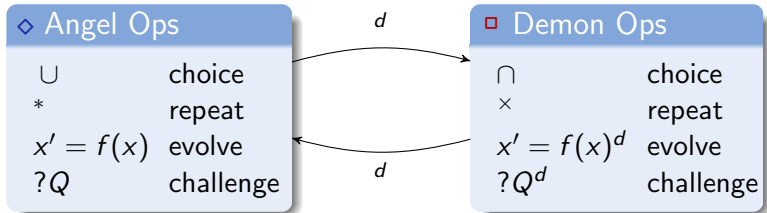


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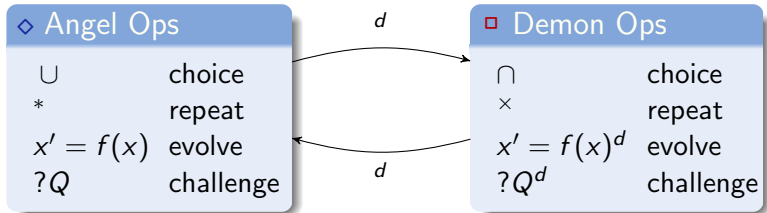


Duality operator  $d$  passes control between players





$\text{if}(Q) \alpha \text{ else } \beta \equiv$   
 $\text{while}(Q) \alpha \equiv$   
 $\alpha \cap \beta \equiv$   
 $\alpha^x \equiv$   
 $(x' = f(x) \& Q)^d \quad x' = f(x) \& Q$   
 $(x := f(x))^d \quad x := f(x)$   
 $?Q^d \quad ?Q$



$\text{if}(Q) \alpha \text{ else } \beta \equiv (?Q; \alpha) \cup (? \neg Q; \beta)$   
 $\text{while}(Q) \alpha \equiv (?Q; \alpha)^*; ? \neg Q$   
 $\alpha \cap \beta \equiv (\alpha^d \cup \beta^d)^d$   
 $\alpha^\times \equiv ((\alpha^d)^*)^d$   
 $(x' = f(x) \& Q)^d \not\equiv x' = f(x) \& Q$   
 $(x := f(x))^d \equiv x := f(x)$   
 $?Q^d \not\equiv ?Q$



$$\begin{aligned}
 & (w - e)^2 \leq 1 \wedge v = f \rightarrow \\
 & \langle ((u := 1 \cap u := -1); \\
 & \quad (g := 1 \cup g := -1); \\
 & \quad t := 0; \\
 & \quad (w' = v, v' = u, e' = f, f' = g, t' = 1 \& t \leq 1)^d \\
 & \rangle^{\times} (w - e)^2 \leq 1
 \end{aligned}$$

EVE at  $e$  plays Angel's part controlling  $g$

WALL·E at  $w$  plays Demon's part controlling  $u$



$$\begin{aligned} & (w - e)^2 \leq 1 \wedge v = f \rightarrow \\ & \langle ((u := 1 \cap u := -1); \\ & \quad (g := 1 \cup g := -1); \\ & \quad t := 0; \\ & \quad (w' = v, v' = u, e' = f, f' = g, t' = 1 \& t \leq 1)^d \\ & \rangle^{\times} \rangle (w - e)^2 \leq 1 \end{aligned}$$

EVE at  $e$  plays Angel's part controlling  $g$

WALL·E at  $w$  plays Demon's part controlling  $u$

EVE assigned environment's time to WALL·E

Definition (Hybrid game  $\alpha$ ) $[[\cdot]] : \text{HG} \rightarrow (\wp(\mathcal{S}) \rightarrow \wp(\mathcal{S}))$ 

$$\varsigma_{x:=f(x)}(X) = \{s \in \mathcal{S} : s_x^{\llbracket f(x) \rrbracket_s} \in X\}$$

$$\varsigma_{x'=f(x)}(X) = \{\varphi(0) \in \mathcal{S} : \varphi(r) \in X, \frac{d\varphi(t)(x)}{dt}(\zeta) = \llbracket f(x) \rrbracket_{\varphi(\zeta)} \text{ for all } \zeta\}$$

$$\varsigma_{?Q}(X) = \llbracket Q \rrbracket \cap X$$

$$\varsigma_{\alpha \cup \beta}(X) = \varsigma_{\alpha}(X) \cup \varsigma_{\beta}(X)$$

$$\varsigma_{\alpha;\beta}(X) = \varsigma_{\alpha}(\varsigma_{\beta}(X))$$

$$\varsigma_{\alpha^*}(X) = \bigcap \{Z \subseteq \mathcal{S} : X \cup \varsigma_{\alpha}(Z) \subseteq Z\}$$

$$\varsigma_{\alpha^d}(X) = (\varsigma_{\alpha}(X^c))^c$$

Definition (dGL Formula  $P$ ) $[[\cdot]] : \text{Fml} \rightarrow \wp(\mathcal{S})$ 

$$[[e \geq \tilde{e}]] = \{s \in \mathcal{S} : [[e]]_s \geq [[\tilde{e}]]_s\}$$

$$[[\neg P]] = (\llbracket P \rrbracket)^c$$

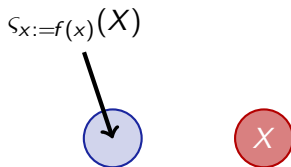
$$[[P \wedge Q]] = \llbracket P \rrbracket \cap \llbracket Q \rrbracket$$

$$[[\langle \alpha \rangle P]] = \varsigma_{\alpha}(\llbracket P \rrbracket)$$

$$[[[\alpha] P]] = \delta_{\alpha}(\llbracket P \rrbracket)$$

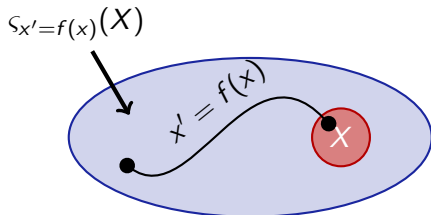
Definition (Hybrid game  $\alpha$ : denotational semantics)

$$s_{x:=f(x)}(X) = \{s \in \mathcal{S} : s_x^{\llbracket f(x) \rrbracket_s} \in X\}$$



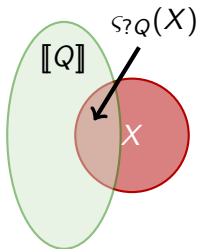
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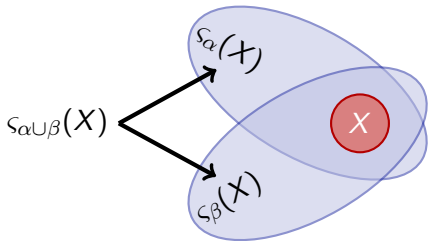
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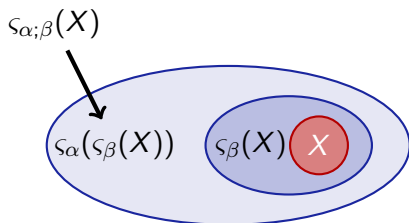
Definition (Hybrid game  $\alpha$ : denotational semantics)

$$s_{\alpha \cup \beta}(X) = s_{\alpha}(X) \cup s_{\beta}(X)$$



Definition (Hybrid game  $\alpha$ : denotational semantics)

$$s_{\alpha;\beta}(X) = s_{\alpha}(s_{\beta}(X))$$







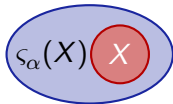
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$$\mathcal{S}_{\alpha^*}(X) =$$



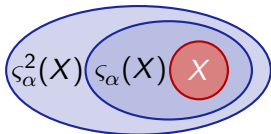
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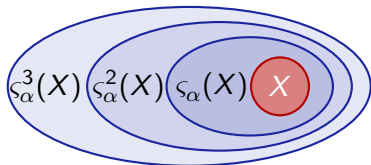
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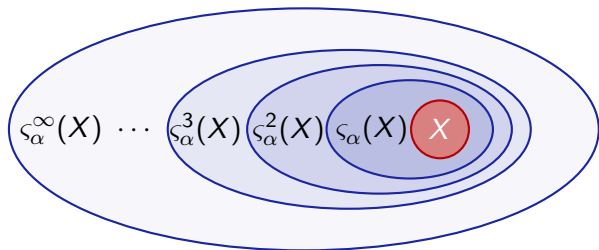
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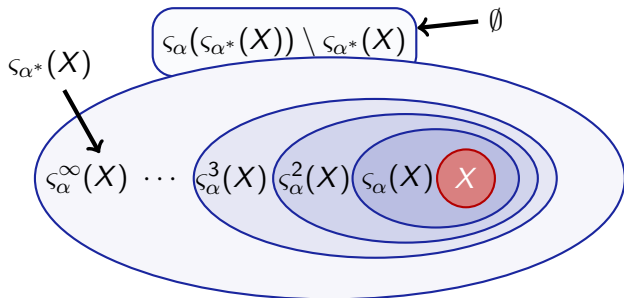
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Definition (Hybrid game  $\alpha$ : denotational semantics)

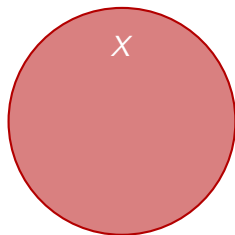
$$\mathcal{S}_\alpha^*(X) = \bigcap \{Z \subseteq \mathcal{S} : X \cup \mathcal{S}_\alpha(Z) \subseteq Z\}$$





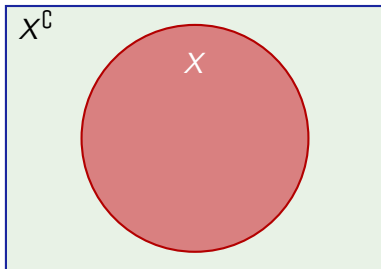
Definition (Hybrid game  $\alpha$ : denotational semantics)

$$S_{\alpha^d}(X) =$$



Definition (Hybrid game  $\alpha$ : denotational semantics)

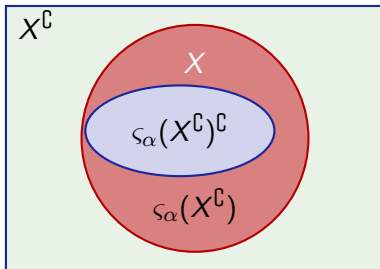
$$S_{\alpha^d}(X) =$$





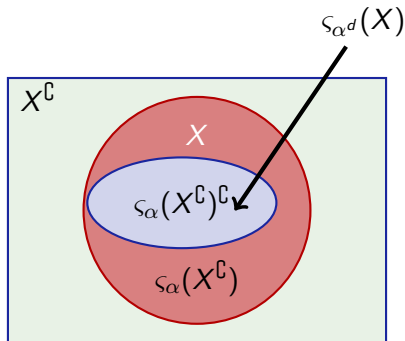
Definition (Hybrid game  $\alpha$ : denotational semantics)

$$S_{\alpha^d}(X) =$$



Definition (Hybrid game  $\alpha$ : denotational semantics)

$$\mathcal{S}_{\alpha^d}(X) = (\mathcal{S}_{\alpha}(X^{\mathbb{C}}))^{\mathbb{C}}$$



Theorem (Consistency & determinacy)

*Hybrid games are consistent and determined, i.e.  $\models \neg\langle\alpha\rangle\neg\phi \leftrightarrow [\alpha]\phi$ .*

Corollary (Determinacy: At least one player wins)

$\models \neg\langle\alpha\rangle\neg\phi \rightarrow [\alpha]\phi$ , *thus*  $\models \langle\alpha\rangle\neg\phi \vee [\alpha]\phi$ .

Corollary (Consistency: At most one player wins)

$\models [\alpha]\phi \rightarrow \neg\langle\alpha\rangle\neg\phi$ , *thus*  $\models \neg([\alpha]\phi \wedge \langle\alpha\rangle\neg\phi)$



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$$[\cdot] \quad [\alpha]P \leftrightarrow \neg\langle\alpha\rangle\neg P$$

$$\langle := \rangle \quad \langle x := f(x) \rangle p(x) \leftrightarrow p(f(x))$$

$$\langle ! \rangle \quad \langle x' = f(x) \rangle P \leftrightarrow \exists t \geq 0 \langle x := y(t) \rangle P$$

$$\langle ? \rangle \quad \langle ?Q \rangle P \leftrightarrow (Q \wedge P)$$

$$\langle \cup \rangle \quad \langle \alpha \cup \beta \rangle P \leftrightarrow \langle \alpha \rangle P \vee \langle \beta \rangle P$$

$$\langle ; \rangle \quad \langle \alpha ; \beta \rangle P \leftrightarrow \langle \alpha \rangle \langle \beta \rangle P$$

$$\langle * \rangle \quad \langle \alpha^* \rangle P \leftrightarrow P \vee \langle \alpha \rangle \langle \alpha^* \rangle P$$

$$\langle d \rangle \quad \langle \alpha^d \rangle P \leftrightarrow \neg\langle \alpha \rangle \neg P$$



$$[\cdot] \quad [\alpha]P \leftrightarrow \neg \langle \alpha \rangle \neg P$$

$$\langle := \rangle \quad \langle x := f(x) \rangle p(x) \leftrightarrow p(f(x))$$

$$\langle ' \rangle \quad \langle x' = f(x) \rangle P \leftrightarrow \exists t \geq 0 \langle x := y(t) \rangle P$$

$$\langle ? \rangle \quad \langle ?Q \rangle P \leftrightarrow (Q \wedge P)$$

$$\langle \cup \rangle \quad \langle \alpha \cup \beta \rangle P \leftrightarrow \langle \alpha \rangle P \vee \langle \beta \rangle P$$

$$\langle ; \rangle \quad \langle \alpha ; \beta \rangle P \leftrightarrow \langle \alpha \rangle \langle \beta \rangle P$$

$$\langle * \rangle \quad \langle \alpha^* \rangle P \leftrightarrow P \vee \langle \alpha \rangle \langle \alpha^* \rangle P$$

$$\langle d \rangle \quad \langle \alpha^d \rangle P \leftrightarrow \neg \langle \alpha \rangle \neg P$$

$$\text{M} \quad \frac{P \rightarrow Q}{\langle \alpha \rangle P \rightarrow \langle \alpha \rangle Q}$$

$$\text{FP} \quad \frac{P \vee \langle \alpha \rangle Q \rightarrow Q}{\langle \alpha^* \rangle P \rightarrow Q}$$

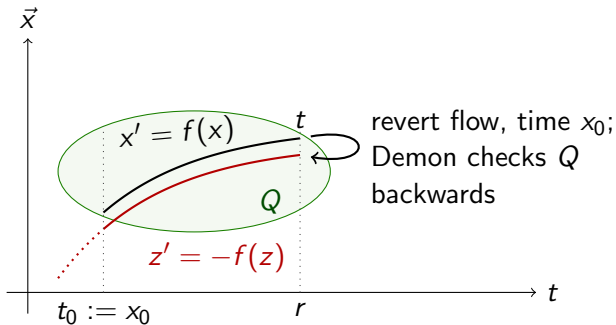
$$\text{MP} \quad \frac{P \quad P \rightarrow Q}{Q}$$

$$\forall \quad \frac{p \rightarrow Q}{p \rightarrow \forall x Q} \quad (x \notin \text{FV}(p))$$

$$\text{US} \quad \frac{\varphi}{\varphi_{p(\cdot)}} \quad \psi(\cdot)$$

# “There and Back Again” Game

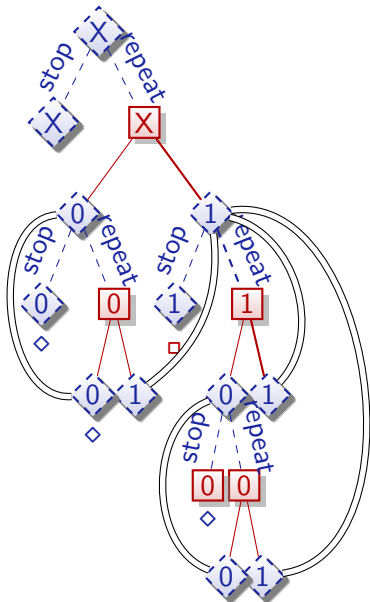
$$x' = f(x) \ \& \ Q \equiv t_0 := x_0; x' = f(x); (z := x; z' = -f(z))^d; ?(z_0 \geq t_0 \rightarrow Q(z))$$



## Lemma

*Evolution domains definable by games*

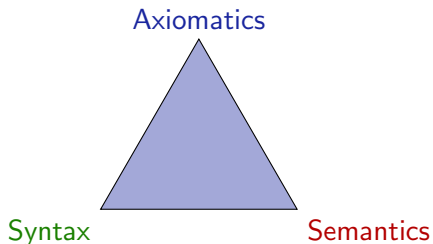
$$\begin{array}{l}
 \mathbb{R} \quad \frac{}{x = 0 \rightarrow 0 = 0 \vee 1 = 0} \\
 \langle := \rangle \quad \frac{}{x = 0 \rightarrow \langle x := 0 \rangle x = 0 \vee \langle x := 1 \rangle x = 0} \\
 \langle \cup \rangle \quad \frac{}{x = 0 \rightarrow \langle x := 0 \cup x := 1 \rangle x = 0} \\
 \langle ^d \rangle \quad \frac{}{x = 0 \rightarrow \neg \langle x := 0 \cap x := 1 \rangle \neg x = 0} \\
 [\cdot] \quad \frac{}{x = 0 \rightarrow [x := 0 \cap x := 1] x = 0} \\
 \text{ind} \quad \frac{}{x = 0 \rightarrow [(x := 0 \cap x := 1)^*] x = 0} \\
 \langle ^d \rangle \quad \frac{}{x = 0 \rightarrow \langle (x := 0 \cup x := 1)^x \rangle x = 0}
 \end{array}$$





## Theorem (Soundness)

*dGL proof calculus is sound i.e. all provable formulas are valid*



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Proof.

$$\langle \cup \rangle \quad \langle \alpha \cup \beta \rangle P \leftrightarrow \langle \alpha \rangle P \vee \langle \beta \rangle P$$

$$\langle ; \rangle \quad \langle \alpha ; \beta \rangle P \leftrightarrow \langle \alpha \rangle \langle \beta \rangle P$$

$$[\cdot] \quad [\alpha] P \leftrightarrow \neg \langle \alpha \rangle \neg P$$

$$M \quad \frac{P \rightarrow Q}{\langle \alpha \rangle P \rightarrow \langle \alpha \rangle Q}$$

□

## Theorem (Soundness)

*dGL proof calculus is sound i.e. all provable formulas are valid*

### Proof.

$$\langle \cup \rangle \quad \llbracket \langle \alpha \cup \beta \rangle P \rrbracket = \varsigma_{\alpha \cup \beta}(\llbracket P \rrbracket) = \varsigma_{\alpha}(\llbracket P \rrbracket) \cup \varsigma_{\beta}(\llbracket P \rrbracket) = \llbracket \langle \alpha \rangle P \rrbracket \cup \llbracket \langle \beta \rangle P \rrbracket = \llbracket \langle \alpha \rangle P \vee \langle \beta \rangle P \rrbracket$$

$$\langle \cup \rangle \quad \langle \alpha \cup \beta \rangle P \leftrightarrow \langle \alpha \rangle P \vee \langle \beta \rangle P$$

$$\langle ; \rangle \quad \llbracket \langle \alpha ; \beta \rangle P \rrbracket = \varsigma_{\alpha ; \beta}(\llbracket P \rrbracket) = \varsigma_{\alpha}(\varsigma_{\beta}(\llbracket P \rrbracket)) = \varsigma_{\alpha}(\llbracket \langle \beta \rangle P \rrbracket) = \llbracket \langle \alpha \rangle \langle \beta \rangle P \rrbracket$$

$$\langle ; \rangle \quad \langle \alpha ; \beta \rangle P \leftrightarrow \langle \alpha \rangle \langle \beta \rangle P$$

$$[\cdot] \text{ is sound by determinacy} \quad [\cdot] \quad [\alpha]P \leftrightarrow \neg \langle \alpha \rangle \neg P$$

**M** Assume the premise  $P \rightarrow Q$  is valid, i.e.  $\llbracket P \rrbracket \subseteq \llbracket Q \rrbracket$ .

Then the conclusion  $\langle \alpha \rangle P \rightarrow \langle \alpha \rangle Q$  is valid, i.e.

$\llbracket \langle \alpha \rangle P \rrbracket = \varsigma_{\alpha}(\llbracket P \rrbracket) \subseteq \varsigma_{\alpha}(\llbracket Q \rrbracket) = \llbracket \langle \alpha \rangle Q \rrbracket$  by monotonicity.

$$\text{M} \quad \frac{P \rightarrow Q}{\langle \alpha \rangle P \rightarrow \langle \alpha \rangle Q}$$

□

## Theorem (Completeness)

*dGL calculus is a sound & complete axiomatization of hybrid games relative to any (differentially) expressive logic  $L$ .*

$$\models \varphi \quad \text{iff} \quad \text{Taut}_L \vdash \varphi$$



## Corollary (Constructive)

*Constructive and Moschovakis-coding-free. (Minimal:  $x' = f(x), \exists, [\alpha^*]$ )*

## Remark (Coquand & Huet)

(Inf.Comput'88)

*Modal analogue for  $\langle \alpha^* \rangle$  of characterizations in Calculus of Constructions*

## Corollary (Meyer & Halpern)

(J.ACM'82)

*$F \rightarrow \langle \alpha \rangle G$  semidecidable for uninterpreted programs.*

## Corollary (Schmitt)

(Inf.Control.'84)

*$[\alpha]$ -free semidecidable for uninterpreted programs.*

## Corollary

*Uninterpreted game logic with even  $d$  in  $\langle \alpha \rangle$  is semidecidable.*



## Corollary

*Harel'77 convergence rule unnecessary for hybrid games, hybrid systems, discrete programs.*

## Corollary (Characterization of hybrid game challenges)

- $[\alpha^*]G$ : Succinct invariants discrete  $\Pi_2^0$
- $[x' = f(x)]G$  and  $\langle x' = f(x) \rangle G$ : Succinct differential (in)variants  $\Delta_1^1$
- $\exists x G$ : Complexity depends on Herbrand disjunctions: discrete  $\Pi_1^1$   
✓ uninterpreted   ✓ reals   ✗  $\exists x [\alpha^*]G$   $\Pi_1^1$ -complete for discrete  $\alpha$

## Corollary (Hybrid version of Parikh's result)

(FOCS'83)

*\*-free dGL complete relative to dL, relative to continuous, or to discrete*

*<sup>d</sup>-free dGL complete relative to dL, relative to continuous, or to discrete*



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set is  $\Pi_n^0$  iff it's  $\{x : \forall y_1 \exists y_2 \forall y_3 \dots y_n \varphi(x, y_1, \dots, y_n)\}$  for a decidable  $\varphi$

set is  $\Sigma_n^0$  iff it's  $\{x : \exists y_1 \forall y_2 \exists y_3 \dots y_n \varphi(x, y_1, \dots, y_n)\}$  for a decidable  $\varphi$

set is  $\Pi_1^1$  iff it's  $\{x : \forall f \exists y \varphi(x, y, f)\}$  for a decidable  $\varphi$  and functions  $f$

set is  $\Sigma_1^1$  iff it's  $\{x : \exists f \forall y \varphi(x, y, f)\}$  for a decidable  $\varphi$  and functions  $f$

$$\Delta_n^i = \Sigma_n^i \cap \Pi_n^i$$



Corollary (ODE Completeness)

(+LICS'12)

*dGL complete relative to ODE for hybrid games with finite-rank Borel winning regions.*

Corollary (Continuous Completeness)

*dGL complete relative to  $L_{\mu D}$ , continuous modal  $\mu$ , over  $\mathbb{R}$*

Corollary (Discrete Completeness)

(+LICS'12)

*dGL + Euler axiom complete relative to discrete  $L_{\mu}$  over  $\mathbb{R}$*





# Soundness & Completeness: Consequences

$$\underbrace{\langle \underbrace{x := 1; x' = 1^d}_{\beta} \cup \underbrace{x := x - 1}_{\gamma} \rangle^*}_{\alpha} 0 \leq x < 1$$

► Fixpoint style proof technique

$\mathbb{R}$	$\forall x (0 \leq x < 1 \vee \forall t \geq 0 p(1+t) \vee p(x-1) \rightarrow p(x)) \rightarrow (true \rightarrow p(x))$
$\langle := \rangle$	$\forall x (0 \leq x < 1 \vee \langle x := 1 \rangle \neg \exists t \geq 0 \langle x := x+t \rangle \neg p(x) \vee p(x-1) \rightarrow p(x)) \rightarrow (true \rightarrow p(x))$
$\langle ' \rangle$	$\forall x (0 \leq x < 1 \vee \langle x := 1 \rangle \neg \langle x' = 1 \rangle \neg p(x) \vee p(x-1) \rightarrow p(x)) \rightarrow (true \rightarrow p(x))$
$\langle ; \rangle, \langle ^d \rangle$	$\forall x (0 \leq x < 1 \vee \langle \beta \rangle p(x) \vee \langle \gamma \rangle p(x) \rightarrow p(x)) \rightarrow (true \rightarrow p(x))$
$\langle \cup \rangle$	$\forall x (0 \leq x < 1 \vee \langle \beta \cup \gamma \rangle p(x) \rightarrow p(x)) \rightarrow (true \rightarrow p(x))$
US	$\forall x (0 \leq x < 1 \vee \langle \alpha \rangle \langle \alpha^* \rangle 0 \leq x < 1 \rightarrow \langle \alpha^* \rangle 0 \leq x < 1) \rightarrow (true \rightarrow \langle \alpha^* \rangle 0 \leq x < 1)$
$\langle * \rangle$	$true \rightarrow \langle \alpha^* \rangle 0 \leq x < 1$



$$K \quad [\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$$

$$\overleftarrow{M} \quad \langle \alpha \rangle (P \vee Q) \rightarrow \langle \alpha \rangle P \vee \langle \alpha \rangle Q$$

$$I \quad [\alpha^*](P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$$

$$B \quad \langle \alpha \rangle \exists x P \rightarrow \exists x \langle \alpha \rangle P$$

$$G \quad \frac{P}{[\alpha]P}$$

$$R \quad \frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha]P_1 \wedge [\alpha]P_2 \rightarrow [\alpha]Q}$$

$$FA \quad \langle \alpha^* \rangle P \rightarrow P \vee \langle \alpha^* \rangle (\neg P \wedge \langle \alpha \rangle P)$$

$$M_{[\cdot]} \quad \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$$

$$M \quad \langle \alpha \rangle P \vee \langle \alpha \rangle Q \rightarrow \langle \alpha \rangle (P \vee Q)$$

$$\forall I \quad (P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$$

$$(x \notin \alpha) \quad \overleftarrow{B} \quad \exists x \langle \alpha \rangle P \rightarrow \langle \alpha \rangle \exists x P$$

$$M_{[\cdot]} \quad \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$$

$$M_{[\cdot]} \quad \frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha](P_1 \wedge P_2) \rightarrow [\alpha]Q}$$

$$\overleftarrow{[*]} \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha^*][\alpha]P$$



# More Axioms ???

~~$\times$~~   $[\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$

$$M_{[\cdot]} \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$$

~~$\leftarrow$~~   $\langle \alpha \rangle (P \vee Q) \rightarrow \langle \alpha \rangle P \vee \langle \alpha \rangle Q$

$$M \langle \alpha \rangle P \vee \langle \alpha \rangle Q \rightarrow \langle \alpha \rangle (P \vee Q)$$

~~$\times$~~   $[\alpha^*](P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$

$$\forall I \quad (P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$$

~~$\times$~~   $\langle \alpha \rangle \exists x P \rightarrow \exists x \langle \alpha \rangle P$

$$(x \notin \alpha) \overleftarrow{B} \quad \exists x \langle \alpha \rangle P \rightarrow \langle \alpha \rangle \exists x P$$

~~$\times$~~   $\frac{P}{[\alpha]P}$

$$M_{[\cdot]} \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$$

~~$\times$~~   $\frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha]P_1 \wedge [\alpha]P_2 \rightarrow [\alpha]Q}$

$$M_{[\cdot]} \frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha](P_1 \wedge P_2) \rightarrow [\alpha]Q}$$

~~$\times$~~   $\langle \alpha^* \rangle P \rightarrow P \vee \langle \alpha^* \rangle (\neg P \wedge \langle \alpha \rangle P)$

~~$\leftarrow$~~   $[\ast] \quad [\alpha^*]P \leftrightarrow P \wedge [\alpha^*][\alpha]P$

Theorem (Axiomatic separation: hybrid systems vs. hybrid games)

*Axiomatic separation is exactly K, I, C, B, V, G. dGL is a subregular, sub-Barcan, monotonic modal logic without loop induction axioms.*

<del>K</del>	$[\alpha](P \rightarrow Q) \rightarrow ([\alpha]P \rightarrow [\alpha]Q)$	$M_{[\cdot]} \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$
<del>M</del>	$\langle \alpha \rangle (P \vee Q) \rightarrow \langle \alpha \rangle P \vee \langle \alpha \rangle Q$	$M \langle \alpha \rangle P \vee \langle \alpha \rangle Q \rightarrow \langle \alpha \rangle (P \vee Q)$
<del>I</del>	$[\alpha^*](P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$	$\forall I (P \rightarrow [\alpha]P) \rightarrow (P \rightarrow [\alpha^*]P)$
<del>B</del>	$\langle \alpha \rangle \exists x P \rightarrow \exists x \langle \alpha \rangle P$	$(x \notin \alpha) \overleftarrow{B} \exists x \langle \alpha \rangle P \rightarrow \langle \alpha \rangle \exists x P$
<del>G</del>	$\frac{P}{[\alpha]P}$	$M_{[\cdot]} \frac{P \rightarrow Q}{[\alpha]P \rightarrow [\alpha]Q}$
<del>R</del>	$\frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha]P_1 \wedge [\alpha]P_2 \rightarrow [\alpha]Q}$	$M_{[\cdot]} \frac{P_1 \wedge P_2 \rightarrow Q}{[\alpha](P_1 \wedge P_2) \rightarrow [\alpha]Q}$
<del>EA</del>	$\langle \alpha^* \rangle P \rightarrow P \vee \langle \alpha^* \rangle (\neg P \wedge \langle \alpha \rangle P)$	$\overleftarrow{[*]} [\alpha^*]P \leftrightarrow P \wedge [\alpha^*][\alpha]P$



- 1 CPS Game Motivation
- 2 Differential Game Logic
  - Syntax
  - Example: Robot Dance
  - Differential Hybrid Games
  - Denotational Semantics
  - Determinacy
- 3 Axiomatization
  - Axiomatics
  - Soundness and Completeness
  - Separating Axioms
- 4 Expressiveness
- 5 Summary



Theorem (Expressive Power: hybrid systems  $<$  hybrid games)

*dGL for hybrid games strictly more expressive than dL for hybrid games:*

$$d\mathcal{L} < dGL$$



Theorem (Expressive Power: hybrid systems < hybrid games)

*dGL for hybrid games strictly more expressive than dL for hybrid games:*

$$d\mathcal{L} < dGL$$

First-order  
adm.  $\mathbb{R}$

Inductive  
adm.  $\mathbb{R}$

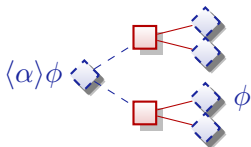


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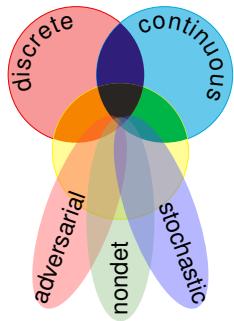


differential game logic

$$\text{dGL} = \text{GL} + \text{HG} = \text{dL} + {}^d$$



- Logic for hybrid games
- Compositional PL + logic
- Discrete + continuous + adversarial
- Winning region iteration  $\geq \omega_1^{\text{CK}}$
- Sound & rel. complete axiomatization
- Hybrid games  $>$  hybrid systems
- ${}^d$  radical challenge yet smooth extension
- Stochastic  $\approx$  adversarial



**Overview**

Cyber-physical systems (CPS) combine cyber capabilities, such as computation or communication, with physical capabilities, such as motion or other physical processes. Cars, aircraft, and robots are prime examples. Because they merge physically in space but are distinguished by discrete computational control algorithms, designing these algorithms is challenging due to their tight coupling with physical behavior. While it is clear that these algorithms are correct, because an algorithm can only run for a finite number of steps, this textbook teaches undergraduate students for some principles behind CPS. It shows them how to design models and analyze, identify safety specifications and control properties, understand simulation and control architectures, design by synthesis, reason algorithmically about CPS models, verify CPS models of appropriate scale, and develop an intuition for operational effects. The book is supported with classical lecture notes, lecture videos, homework assignments, and lab assignments.

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- 2 State and Control
- 3 Safety and Control
- 4 Dynamical Systems and Dynamic Systems
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- 6 Control of Rotations
- 7 Invariant and Invariant

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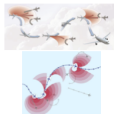
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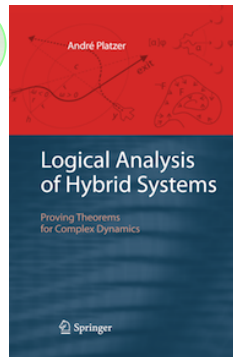


**Comments**

"This excellent textbook teaches design and analysis of cyber-physical systems with a logical and computational way of thinking. The presentation is exemplary for finding the right balance between rigorous mathematical formalism and illustrative case studies aimed at practical students in control design."  
 [Rajar Aiyar, University of Pennsylvania]

"The author has developed major important tools for the design and control of these cyber-physical systems that increasingly shape our lives. This book is a 'must' for anyone interested, engineer, and mathematicians designing cyber-physical systems."  
 [Andrzej Nowak, Cornell University]

"This book provides a wonderful introduction to cyber-physical systems, covering fundamental concepts from computer science and control theory, from the perspective of formal logic. The material is brought to life through many diverse examples, illustrations, and exercises. A wealth of background material is provided in the text and in an appendix for each chapter, which makes the book self-contained and accessible to university students of all levels."  
 [Srinivas Aravamudan, Université Grenoble Alpes]





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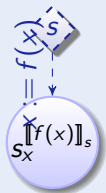
doi:10.1007/978-3-642-14509-4.



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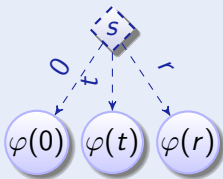


## 6 Operational Semantics

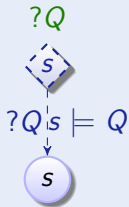
Definition (Hybrid game  $\alpha$ : operational semantics) $x := f(x)$ 

Definition (Hybrid game  $\alpha$ : operational semantics)

$$x' = f(x) \& Q$$



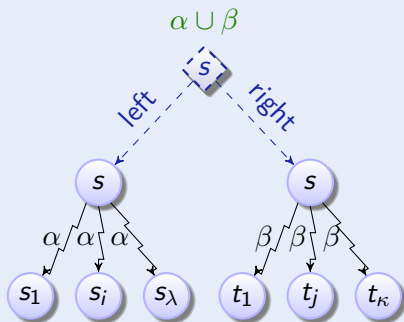
Definition (Hybrid game  $\alpha$ : operational semantics)





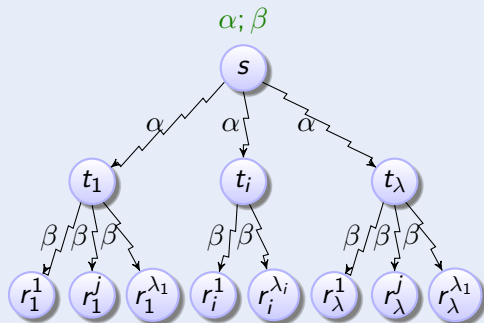


Definition (Hybrid game  $\alpha \cup \beta$ : operational semantics)



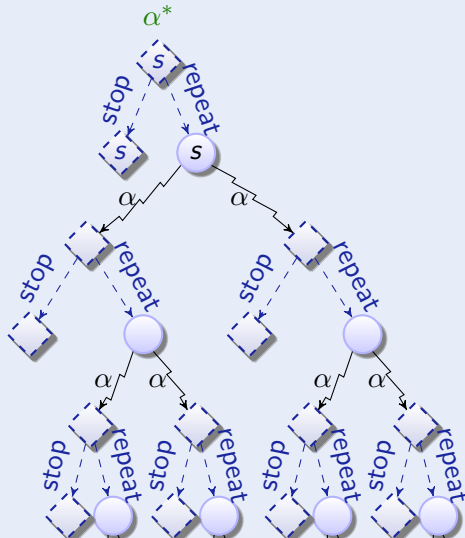


## Definition (Hybrid game $\alpha; \beta$ : operational semantics)





## Definition (Hybrid game $\alpha$ : operational semantics)





## Definition (Hybrid game $\alpha$ : operational semantics)

