

Pegasus: a framework for sound continuous invariant generation

Andrew Sogokon^{2,1}, Stefan Mitsch¹, Yong Kiam Tan¹, Katherine Cordwell¹,
and André Platzer¹

¹Carnegie Mellon University, USA

²University of Southampton, UK

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Introduction

What this talk is about

Theorem proving in cyber-physical systems (CPS).

Why? Fully rigorous proofs of correctness.

Important for safety-critical embedded systems.

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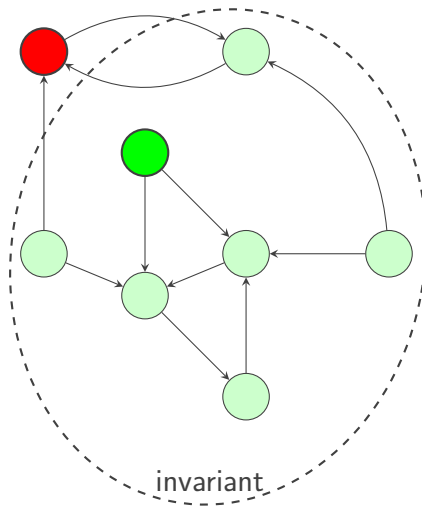
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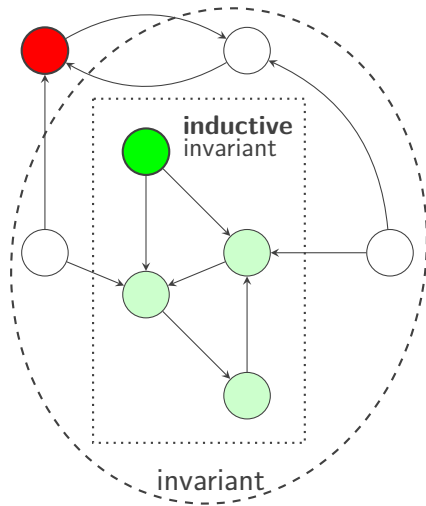
Problem: Theorem proving in CPS is not fully automatic.

Safety verification relies on finding the right invariants.

Invariants in verification



Invariants in verification



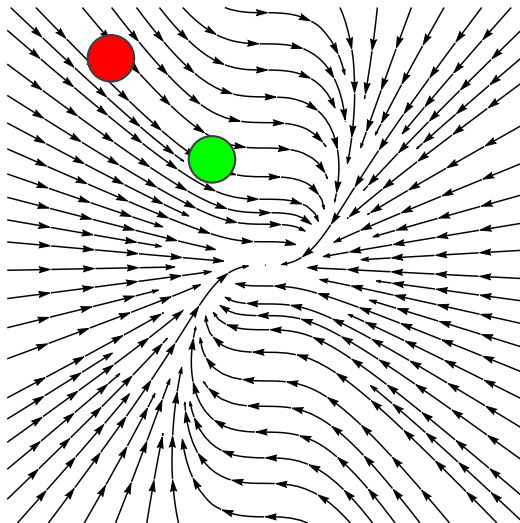
Continuous invariants

ODEs:

$$\vec{x}' = f(\vec{x})$$

$$\vec{x} \in \mathbb{R}^n$$

$$\text{Init} \subseteq \mathbb{R}^n$$



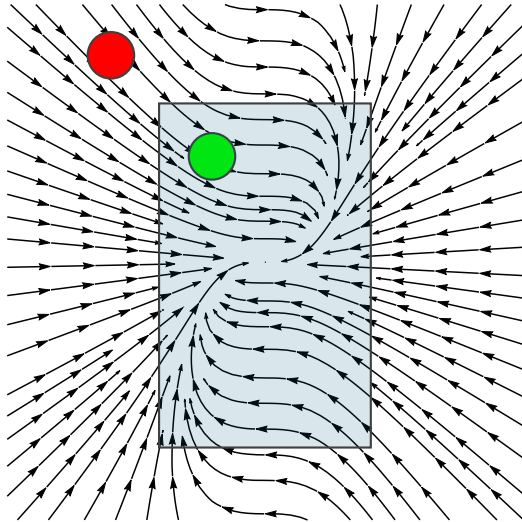
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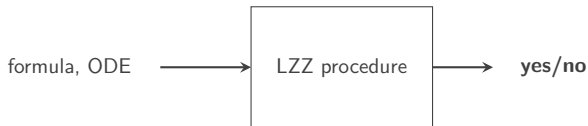


Checking continuous invariants

Checking whether a formula defines a continuous (inductive) invariant is **decidable** (Liu, Zhan & Zhao, EMSOFT 2011).

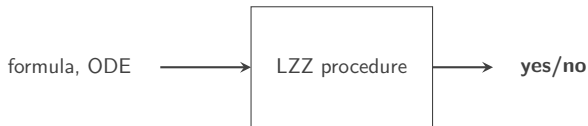
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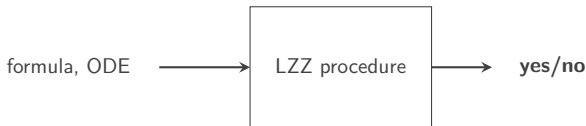
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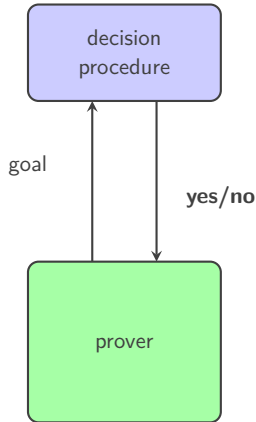


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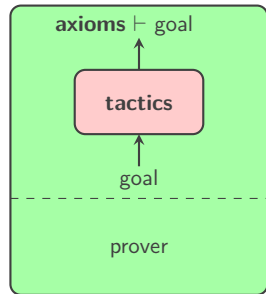


Handling decidable problems

Design choices in proof assistants



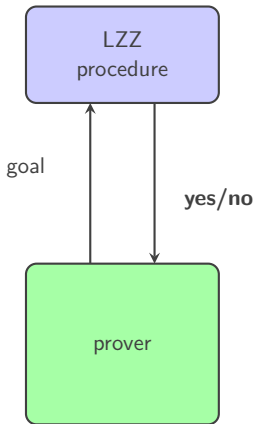
Using external oracles



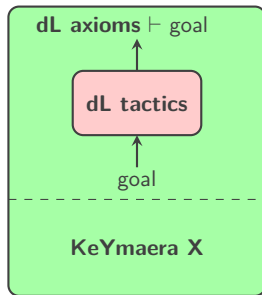
Formal proof using tactics

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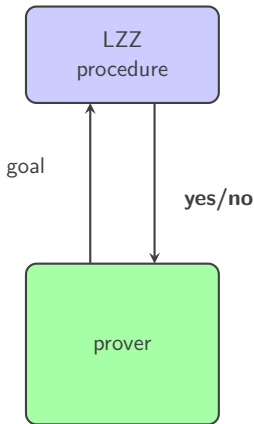
“PVS-style”



LCF-style

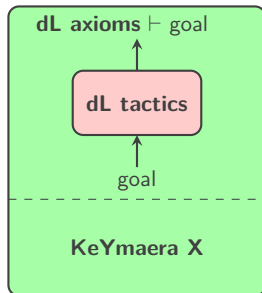
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“PVS-style”

Less soundness-critical code



LCF-style

Generating continuous invariants

Excellent progress made this decade on the **invariant checking problem**.

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$$\frac{pre \rightarrow inv \quad inv \rightarrow [ODE] inv \quad inv \rightarrow post}{pre \rightarrow [ODE] post}$$

Practical bottleneck for proof automation.

Generating continuous invariants

In theory, we can search for invariants using **template formulas**:

$$a_0 + a_1x + a_2y + a_3x^2 + a_4xy + a_5y^2 < 0 \wedge b_0 + b_1x + b_2y \geq 0$$

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More practical alternatives are needed.

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More practical methods for invariant generation exist.

These are

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- ▶ have different strengths and limitations,
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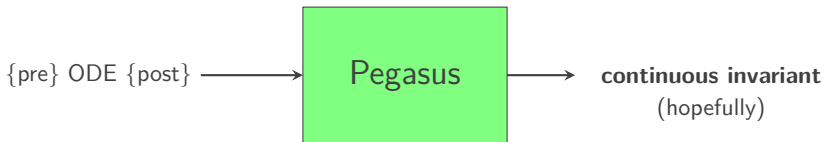
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- ▶ create a wide spectrum for what can be tried.

Challenge:

- ▶ build a **system for navigating this spectrum**,
- ▶ use it to improve proof automation in KeYmaera X.

Continuous invariant generator

Pegasus is an automatic continuous invariant generator.

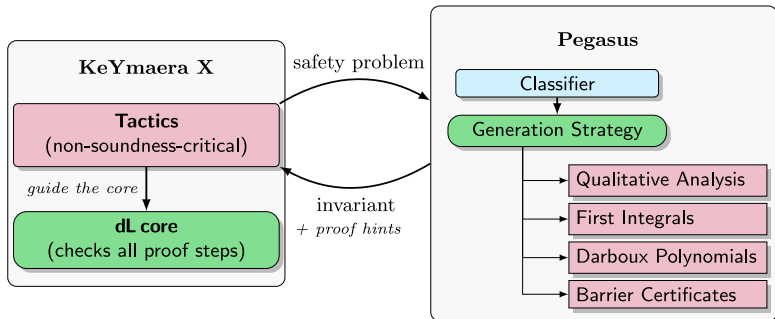


<http://pegasus.keymaeraX.org>

As of version 1.0, Pegasus (implemented in Wolfram Language) has

- ▶ a simple continuous safety verification problem classifier,
- ▶ implementation of invariant generation methods,
- ▶ a strategy for combining invariant generation methods,
- ▶ proof hints for KeYmaera X.

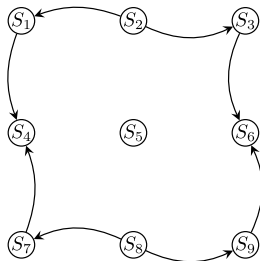
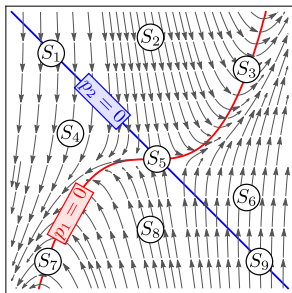
Sound integration architecture



Discrete abstraction

Partition \mathbb{R}^n into discrete states S_1, \dots, S_k defined by some predicates.

Compute the discrete transition relation.

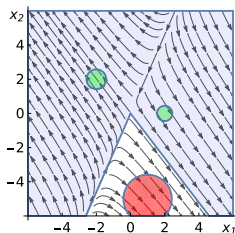


Qualitative analysis

In essence: discrete abstraction using information in the problem.

Some sources of predicates:

- ▶ right-hand sides of ODEs, their factors, etc.
- ▶ functions defining the pre/postcondition
- ▶ physically meaningful quantities (e.g. divergence of the vector field)



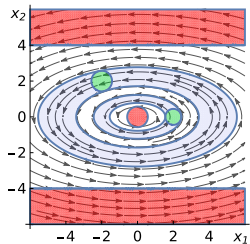
First integrals

and Darboux polynomials

Conserved quantities in the continuous system.

Functions p such that $p' = 0$ (i.e. the rate of change of p w.r.t. f is 0).

Searching for **polynomial** first integrals (of bounded degree) can be done using linear algebra.



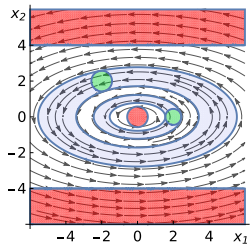
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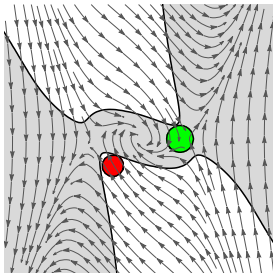


Darboux polynomials: $p' = \alpha p$, where α is a polynomial.

Barrier certificates

Main idea: find a continuous invariant $p \leq 0$ using

- ▶ **differential inequalities**, e.g. $p' \leq 0$, $p' \leq \lambda p$ ($\lambda \in \mathbb{R}$), and
- ▶ **sum-of-squares decomposition** (via semidefinite programming).



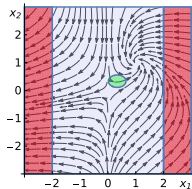
First described by Prajna and Jadbabaie (HSCC 2004).

Generalizes to **vector barrier certificates** (our work, FM 2018).

Differential saturation

A strategy for combining invariant generation methods.

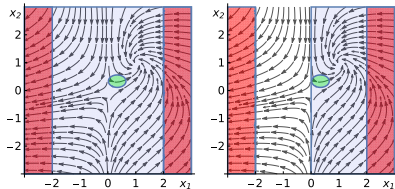
Iteratively refine the invariant using available methods.



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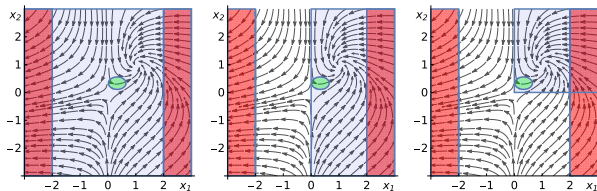


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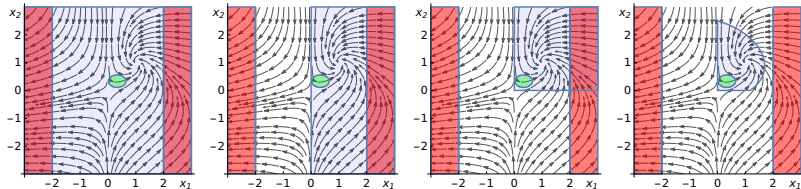


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- ▶ Refinement 2 (using Qualitative analysis)

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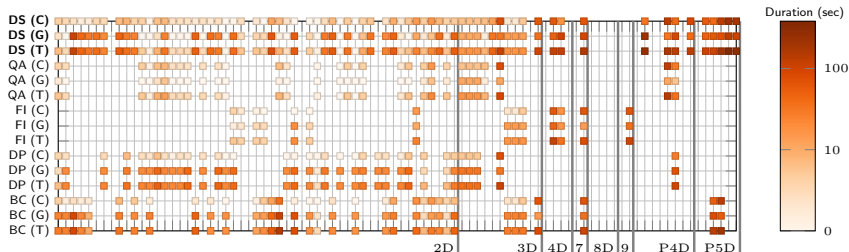


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- ▶ Refinement 3 (using a barrier certificate)

Some results

Non-linear systems

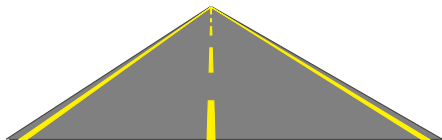
- ▶ 90 benchmark safety verification problems from the literature.
- ▶ 71 problem could be solved by the combined strategy.



Non-linear problems (dimension: 2D-9D, followed by 4D and 5D product systems)

- ▶ A few problems were **only** solved by the combined strategy (no individual method succeeded by itself).

Conclusion & future outlook

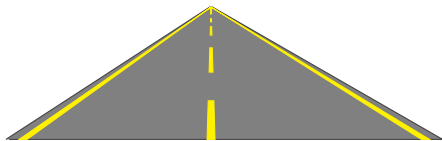


The results we observe are thus far very encouraging.

- ▶ Many more invariant generation methods to implement.
- ▶ Generation strategies that work solely in tractable theories.
- ▶ Larger corpus of continuous verification problems needed.

Goal: to make hybrid systems theorem proving more or less **automatic**.

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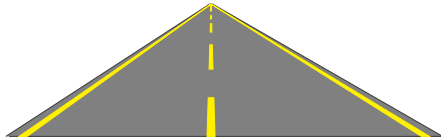
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