15-819M: Data, Code, Decisions

07: Reasoning about While Programs with Dynamic Logic

André Platzer

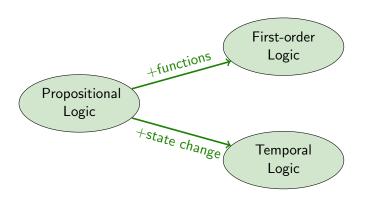
aplatzer@cs.cmu.edu Carnegie Mellon University, Pittsburgh, PA

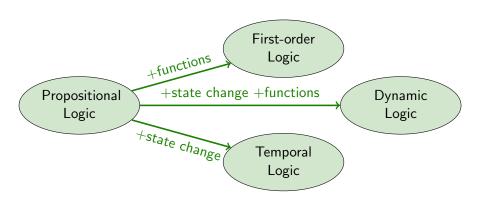
Outline

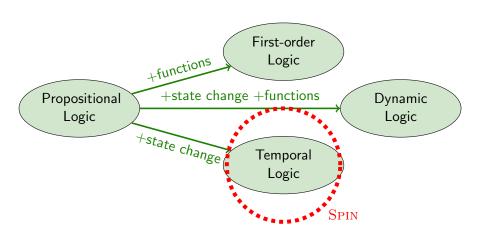
- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions

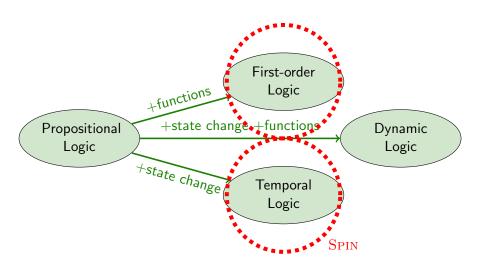
Outline

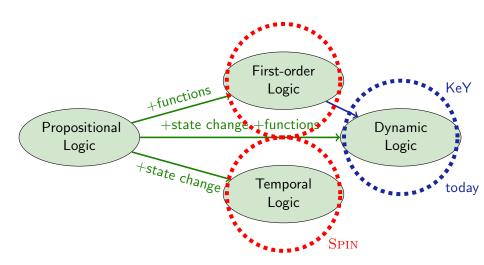
- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- 2 DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions











State Dependence of Formula Evaluation

Closed FOL formula either evaluates to true or false in a model \mathcal{M} Consider model $\mathcal{M}=(\mathcal{D},\delta,\mathcal{I})$ as program state

Let x be (local) program variable or attribute Execution of program p may change program state, i.e., value of x

State Dependence of Formula Evaluation

Closed FOL formula either evaluates to true or false in a model \mathcal{M} Consider model $\mathcal{M}=(\mathcal{D},\delta,\mathcal{I})$ as program state

Let x be (local) program variable or attribute Execution of program p may change program state, i.e., value of x

Example

Executing x=3; results in \mathcal{M} such that $\mathcal{M} \models x \doteq 3$

Executing x=4; results in $\mathcal M$ such that $\mathcal M \not\models x \doteq 3$

State Dependence of Formula Evaluation

Closed FOL formula either evaluates to true or false in a model \mathcal{M} Consider model $\mathcal{M}=(\mathcal{D},\delta,\mathcal{I})$ as program state

Let x be (local) program variable or attribute Execution of program p may change program state, i.e., value of x

Example

Executing x=3; results in \mathcal{M} such that $\mathcal{M} \models x \doteq 3$ Executing x=4; results in \mathcal{M} such that $\mathcal{M} \not\models x \doteq 3$

Need a logic to capture state before/after program execution

Rigid versus Flexible Symbols

Signature of program logic defined as in FOL, but: In addition there are program variables, attributes, etc.

Rigid versus Flexible Symbols

- Rigid symbols have same interpretation in all program states
 - First-order variables (logical variables for quantification)
 Used to hold initial values of program variables
 - Built-in functions and predicates such as 0,1,...,+,*,...,<,...
- Flexible (or non-rigid) symbols where interpretation depends on state

Capture side effects on state during program execution

Functions modeling program variables and attributes are flexible

Any term containing at least one flexible symbol is also flexible

Signature of Dynamic Logic (Simple Version)

Definition (Dynamic Logic Signature)

```
First-order signature \Sigma = (\mathsf{PSym}_r, \, \mathsf{FSym}_r, \, \mathsf{FSym}_{nr}, \, \alpha)
Rigid predicate symbols \mathsf{PSym} = \{>, >=, \ldots\}
Rigid function symbols \mathsf{FSym} = \{+, -, *, 0, 1, \ldots, \mathbf{true}, \, \mathbf{false}\}
Flexible function symbols \mathsf{FSym} = \{i, j, k, \ldots, p, q, r, \ldots\}
```

Type hierarchy

```
T = \{\bot, int, boolean, \top\} with int, boolean incomparable Standard typing: boolean true; <(int,int);, etc.
```

Variables

Definition (First-Order/Logical Variables)

Typed logical variables (rigid), declared as T x;

Definition

Program Variables Flexible constants int i; boolean p used as program variables

Terms

- First-order terms defined as in FOL
- First-order terms may contain rigid and flexible symbols
- $\mathsf{FSym}_r \cap \mathsf{FSym}_{nr} = \emptyset$

Example

Signature for $FSym_{nr}$: int j; boolean p Variables int x; boolean b;

- j and j+x are flexible terms of type int
- p is a flexible term of type boolean
- x + x is a rigid term of type int
- \bullet j+b and j+p are not well-typed

Atomic Programs

Definition (Atomic Programs)

The atomic programs Π_0 are assignments of the form j = t where:

- T j; is a program variable (flexible constant)
- t is a first-order term of type T without logical variables

Example

```
Signature for FSym_{nr}: int j; boolean p Variables int x; boolean b;
```

- j=j+1, j=0 and p=false are assignments
- j=j+x contains a logical variable on the right
- x=1 contains a logical variable on the left
- j=j is equality, not assignment
- p=0 is ill-typed

Dynamic Logic Programs (Simple Version)

Definition (Program)

Inductive definition of the set of (DL) programs Π :

- If π is an atomic program, then π ; is a program
- If p and q are programs, then pq is a program
- ullet If b is a variable-free term of type boolean, p and q programs, then

```
if (b) p else q; if (b) p; are programs
```

If b is a variable-free term of type boolean, p a program, then while (b) p;
 is a program

Dynamic Logic Programs (Simple Version)

Definition (Program)

Inductive definition of the set of (DL) programs Π :

- If π is an atomic program, then π ; is a program
- If p and q are programs, then pq is a program
- If b is a variable-free term of type boolean, p and q programs, then

```
if (b) p else q; if (b) p; are programs
```

If b is a variable-free term of type boolean, p a program, then while (b) p;
 is a program

Programs contain no logical variables!

Dynamic Logic Programs

```
Example (Admissible Program)
Signature for FSym_{nr}: int r; int i; int n;
Signature for FSym<sub>r</sub>: int 0; int +(int,int); int -(int,int);
Signature for PSym<sub>r</sub>: <(int,int);
   i=0:
  r=0:
   while (i < n) {
      i=i+1;
     r=r+i;
   };
   r=r+r-n;
```

Dynamic Logic Programs

```
Example (Admissible Program)
Signature for FSym_{nr}: int r; int i; int n;
Signature for FSym<sub>r</sub>: int 0; int +(int,int); int -(int,int);
Signature for PSym<sub>r</sub>: <(int,int);
   i=0:
  r=0:
   while (i < n) {
      i=i+1;
     r=r+i;
   };
   r=r+r-n;
```

Which value does the program compute in r?

Dynamic Logic Formulas (Simple Version)

Definition (Dynamic Logic Formulas (DL Formulas))

- Each FOL formula is a DL formula
- If p is a program and ϕ a DL formula then $\langle p \rangle \phi$ is a DL formula
- If p is a program and ϕ a DL formula then $[p]\phi$ is a DL formula
- DL formulas closed under FOL quantifiers and connectives

Dynamic Logic Formulas (Simple Version)

Definition (Dynamic Logic Formulas (DL Formulas))

- Each FOL formula is a DL formula
- If p is a program and ϕ a DL formula then $\langle p \rangle \phi$ is a DL formula
- ullet If p is a program and ϕ a DL formula then $[p]\phi$ is a DL formula
- DL formulas closed under FOL quantifiers and connectives

- Program variables are flexible constants: never bound in quantifiers
- Program variables need not be declared or initialized in program
- Programs contain no logical variables
- Modalities can be arbitrarily nested

•
$$\forall$$
 int y ; $((\langle x = 1; \rangle x \doteq y) \iff (\langle x = 1*1; \rangle x \doteq y))$

Example (Well-formed? If yes, under which signature?)

• \forall int y; (($\langle x = 1; \rangle x \doteq y$) <-> ($\langle x = 1*1; \rangle x \doteq y$)) Well-formed if FSym_{nr} contains int x;

- \forall int y; (($\langle x = 1; \rangle x \doteq y$) <-> ($\langle x = 1*1; \rangle x \doteq y$)) Well-formed if FSym_{nr} contains int x;
- $\exists \operatorname{int} x$; $[x = 1;](x \doteq 1)$

- \forall int y; (($\langle x = 1; \rangle x \doteq y$) \iff ($\langle x = 1*1; \rangle x \doteq y$)) Well-formed if FSym_{nr} contains int x;
- ∃ int x; [x = 1;](x = 1)
 Not well-formed, because logical variable occurs in program

- \forall int y; (($\langle x = 1; \rangle x \doteq y$) \iff ($\langle x = 1*1; \rangle x \doteq y$)) Well-formed if FSym_{nr} contains int x;
- ∃ int x; [x = 1;](x = 1)
 Not well-formed, because logical variable occurs in program
- $\langle x = 1; \rangle ([while (true) {};]false)$

- \forall int y; (($\langle x = 1; \rangle x \doteq y$) \iff ($\langle x = 1*1; \rangle x \doteq y$)) Well-formed if FSym_n contains int x;
- ∃ int x; [x = 1;](x = 1)
 Not well-formed, because logical variable occurs in program
- $\langle x = 1; \rangle$ ([while (true) {};]false) Well-formed if $FSym_{nr}$ contains int x; program formulas can be nested

Outline

- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- 4 Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions

Dynamic Logic Semantics: States

First-order model can be considered as program state

- Interpretation of flexible symbols can change from state to state (program variables, attribute values)
- Interpretation of rigid symbols is the same in all states (built-in functions and predicates)

States as first-order models

From now, consider program state as first-order model $\mathcal{M} = (\mathcal{D}, \delta, \mathcal{I})$

- Only interpretation $\mathcal I$ of flexible symbols in FSym_{nr} can change \Rightarrow only track values of $f \in \mathsf{FSym}_{nr}$: use s (for state) instead of $\mathcal M$
- Set of all states s is S

Definition (Kripke Structure / Labelled Transition System)

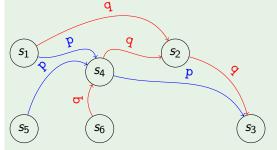
Kripke structure or Labelled transition system $K = (S, \rho)$

- State (=first-order model) $s = (\mathcal{D}, \delta, \mathcal{I}) \in S$
- Transition relation $\rho:\Pi\to (S\to S)$
 - $m{\bullet}$ ho is the operational semantics of programs Π
 - Each program $p \in \Pi$ transforms a start state s into end state $\rho(p)(s)$
 - $\rho(p)(s)$ can be undefined: p does not terminate when started in s
 - Our programs are deterministic (unlike PROMELA): $\rho(p)$ is a (partial) function (at most one value)

Example (Kripke Structure)

Two programs p and q

Show $\rho(p)$ and $\rho(q)$, states $S = \{s1, \ldots, s_6\}$



When p is started in s_5 it terminates in s_4 , etc.

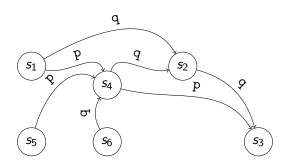
In general, Π and S are infinite!

Semantic Evaluation of Program Formulas

Definition (Validity Relation for Program Formulas)

- $s, \beta \models \langle p \rangle \phi$ iff $\rho(p)(s), \beta \models \phi$ and $\rho(p)(s)$ is defined p terminates and ϕ is true in the final state after execution
- $s, \beta \models [p]\phi$ iff $\rho(p)(s), \beta \models \phi$ whenever $\rho(p)(s)$ is defined

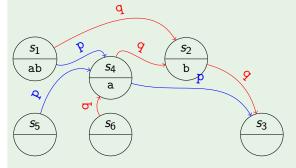
 If p terminates then ϕ is true in the final state after execution



Example (Semantic Evaluation of Program Formulas)

Signature FSym_{nr}: boolean a; boolean b;

Notation: $\mathcal{I}(x) = T$ iff x appears in node

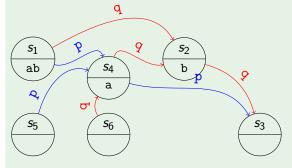


Question 1: $s_1 \models \langle p \rangle (a \doteq true)$?

Example (Semantic Evaluation of Program Formulas)

Signature FSym_{nr}: boolean a; boolean b;

Notation: $\mathcal{I}(x) = T$ iff x appears in node

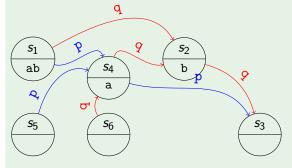


Question 2: $s_1 \models \langle q \rangle (a \doteq true)$?

Example (Semantic Evaluation of Program Formulas)

Signature FSym_{nr}: boolean a; boolean b;

Notation: $\mathcal{I}(x) = T$ iff x appears in node



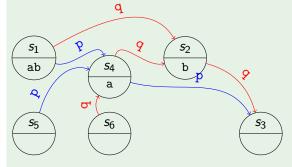
Question 3: $s_5 \models \langle q \rangle (a \doteq true)$?

Dynamic Logic Semantics: Kripke Structure

Example (Semantic Evaluation of Program Formulas)

Signature FSym_{nr}: boolean a; boolean b;

Notation: I(x) = T iff x appears in node



Question 4: $s_5 \models [q](a \doteq true)$?

Program Correctness

Definition (Notions of Program Correctness)

- If $s, \beta \models \langle p \rangle \phi$ then p totally correct (with respect to ϕ) in s, β
- If $s, \beta \models [p]\phi$ then p partially correct (with respect to ϕ) in s, β
- Duality $\langle \mathbf{p} \rangle \phi$ iff $![\mathbf{p}]! \phi$ Exercise: justify this using the semantics
- Implication if $\langle \mathbf{p} \rangle \phi$ then $[\mathbf{p}] \phi$ Total correctness implies partial correctness
 - converse is false
 - holds only for deterministic programs!

Semantics of Sequents

 $\Gamma=\{\phi_1,\ldots,\phi_n\}$ and $\Delta=\{\psi_1,\ldots,\psi_m\}$ sets of program formulas where all logical variables occur bound

Recall:
$$s \models (\Gamma \Rightarrow \Delta)$$
 iff $s \models (\phi_1 \& \cdots \& \phi_n) \rightarrow (\psi_1 \mid \cdots \mid \psi_m)$

Define semantics of DL sequents like semantics of FOL sequents

Definition (Validity of Sequents over Program Formulas)

A sequent $\Gamma \Longrightarrow \Delta$ over program formulas is valid iff

$$s \models (\Gamma \Longrightarrow \Delta)$$
 in all states s

Semantics of Sequents

 $\Gamma=\{\phi_1,\ldots,\phi_n\}$ and $\Delta=\{\psi_1,\ldots,\psi_m\}$ sets of program formulas where all logical variables occur bound

Recall:
$$s \models (\Gamma \Longrightarrow \Delta)$$
 iff $s \models (\phi_1 \& \cdots \& \phi_n) \implies (\psi_1 \mid \cdots \mid \psi_m)$

Define semantics of DL sequents like semantics of FOL sequents

Definition (Validity of Sequents over Program Formulas)

A sequent $\Gamma \Longrightarrow \Delta$ over program formulas is valid iff

$$s \models (\Gamma \Longrightarrow \Delta)$$
 in all states s

Consequence for program variables

Initial value of program variables implicitly "universally quantified"

Initial States

JAVA initial states

KeY prover "starts" programs in initial states according to JAVA convention:

- Values of array entries initialized to default values: int[] to 0, etc.
- Static object initialization
- No objects created

How to restrict validity to set of initial states $S_0 \subseteq S$?

- Design closed FOL formula Init with
 - $s \models \text{Init}$ iff $s \in S_0$
- 2 Use sequent $\Gamma, \operatorname{Init} \Longrightarrow \Delta$

Later: simple method for specifying initial value of program variables

Outline

- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions

Operational Semantics of Programs

In labelled transition system $K = (S, \rho)$: $\rho : \Pi \to (S \to S)$ is operational semantics of programs $p \in \Pi$

How is ρ defined for concrete programs and states?

Operational Semantics of Programs

In labelled transition system $K = (S, \rho)$: $\rho : \Pi \to (S \to S)$ is operational semantics of programs $p \in \Pi$

How is ρ defined for concrete programs and states?

Example (Operational semantics of assignment)

State s interprets flexible symbols f with $\mathcal{I}_s(f)$

$$ho(\mathtt{x=t})(s) = s'$$
 where s' identical to s except $\mathcal{I}_{s'}(x) = \mathit{val}_s(t)$

Very tedious task to define ρ for JAVA . . . \Rightarrow here we go directly to calculus for program formulas!

Outline

- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- 4 Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions

Sequent calculus decomposes top-level operator in formula What is "top-level" in a sequential program p; q; r?

Symbolic Execution (King, late 60s)

- Follow the natural control flow when analyzing a program
- Values of some variables unknown: symbolic state representation

Sequent calculus decomposes top-level operator in formula What is "top-level" in a sequential program p; q; r?

Symbolic Execution (King, late 60s)

- Follow the natural control flow when analyzing a program
- Values of some variables unknown: symbolic state representation

Example

Compute the final state after termination of

```
int x; int y; x=x+y; y=x-y; x=x-y;
```

General form of rule conclusions in symbolic execution calculus

```
\langle \mathtt{stmt}; \ \mathtt{rest} \rangle \phi, \qquad [\mathtt{stmt}; \ \mathtt{rest}] \phi
```

- Rules must symbolically execute first statement
- Repeated application of rules in a proof corresponds to symbolic program execution

Symbolic execution of assignment

 \mathbf{x}_{old} new program variable that "rescues" old value of \mathbf{x}

Symbolic execution of assignment

$$\text{assign } \frac{\{\mathbf{x}/\mathbf{x}_{\textit{old}}\}\Gamma,\;\mathbf{x} \doteq \{\mathbf{x}/\mathbf{x}_{\textit{old}}\}t \quad \Longrightarrow \quad \langle \mathbf{rest}\rangle\phi,\; \{\mathbf{x}/\mathbf{x}_{\textit{old}}\}\Delta}{\Gamma \Longrightarrow \langle \mathbf{x} \; = \; \mathbf{t};\; \mathbf{rest}\rangle\phi,\Delta}$$

 \mathbf{x}_{old} new program variable that "rescues" old value of \mathbf{x}

Example

Conclusion matching:
$$\{x/x\}$$
, $\{t/x+y\}$, $\{rest/y=x-y; x=x-y;\}$, $\{\phi/(x \doteq y_0 \& y \doteq x_0)\}$, $\{\Gamma/x \doteq x_0, y \doteq y_0\}$, $\{\Delta/\emptyset\}$

$$\begin{array}{c} \mathbf{x}_{old} \doteq x_0, \ \mathbf{y} \doteq y_0, \ \mathbf{x} \doteq \mathbf{x}_{old} + \mathbf{y} \Longrightarrow \langle \mathbf{y} = \mathbf{x} - \mathbf{y}; \ \mathbf{x} = \mathbf{x} - \mathbf{y}; \rangle (\mathbf{x} \doteq y_0 \& \mathbf{y} \doteq x_0) \\ \mathbf{x} \doteq x_0, \ \mathbf{y} \doteq y_0 \Longrightarrow \langle \mathbf{x} = \mathbf{x} + \mathbf{y}; \ \mathbf{y} = \mathbf{x} - \mathbf{y}; \rangle (\mathbf{x} \doteq y_0 \& \mathbf{y} \doteq x_0) \end{array}$$

Proving Partial Correctness

Partial correctness assertion

If program p is started in a state satisfying Pre and terminates, then its final state satisfies Post

In Hoare logic {Pre} p {Post}

In DL Pre \rightarrow [p]Post

(Pre, Post must be FOL)

(Pre, Post any DL formula)

Proving Partial Correctness

Partial correctness assertion

If program p is started in a state satisfying Pre and terminates, then its final state satisfies Post

Example (In KeY Syntax, automatic proof)

lect11/swap.key

(Demo)

Example

$$\forall T y; ((\langle p \rangle x \stackrel{.}{=} y) \iff (\langle q \rangle x \stackrel{.}{=} y))$$

Example

$$\forall T y; ((\langle p \rangle x \stackrel{.}{=} y) \iff (\langle q \rangle x \stackrel{.}{=} y))$$

Not valid in general

Programs p behave q equivalently on variable T x

Example

$$\forall T y; ((\langle p \rangle x \stackrel{.}{=} y) \iff (\langle q \rangle x \stackrel{.}{=} y))$$

Not valid in general

Programs p behave q equivalently on variable T x

Example

$$\exists \ T \ y; \ (x \doteq y \ -\!\!\!> \ \langle p \rangle true)$$

Example

$$\forall T y; ((\langle p \rangle x \stackrel{.}{=} y) \iff (\langle q \rangle x \stackrel{.}{=} y))$$

Not valid in general

Programs p behave q equivalently on variable T x

Example

$$\exists T y$$
; $(x \doteq y \rightarrow \langle p \rangle true)$

Not valid in general

Program p terminates in all states where x has suitable initial value

Symbolic execution of conditional

Symbolic execution must consider all possible execution branches

Symbolic execution of conditional

$$\text{if } \frac{ \Gamma, \texttt{b} \doteq \mathbf{true} \Longrightarrow \langle \texttt{p}; \ \mathtt{rest} \rangle \phi, \Delta \qquad \Gamma, \texttt{b} \doteq \mathbf{false} \Longrightarrow \langle \texttt{q}; \ \mathtt{rest} \rangle \phi, \Delta }{ \Gamma \Longrightarrow \langle \mathbf{if} \ (\texttt{b}) \ \{ \ \texttt{p} \ \} \ \mathsf{else} \ \{ \ \texttt{q} \ \} \ ; \ \mathtt{rest} \rangle \phi, \Delta }$$

Symbolic execution must consider all possible execution branches

Symbolic execution of loops: unwind

$$\begin{array}{c} \text{unwindLoop} \ \ \, \frac{\Gamma \Longrightarrow \big\langle \text{if (b) \{ p; while (b) p\}; r} \big\rangle \phi, \Delta}{\Gamma \Longrightarrow \big\langle \text{while (b) \{p\}; r} \big\rangle \phi, \Delta} \end{array}$$

How to express correctness for any initial value of program variable?

How to express correctness for any initial value of program variable?

Not allowed: $\forall T \ i; \langle \dots i \dots \rangle \phi$ (program \neq logical variable)

How to express correctness for any initial value of program variable?

```
Not allowed: \forall T \ i; \langle \dots i \dots \rangle \phi (program \neq logical variable)
```

Not intended:
$$\Rightarrow \langle ...i... \rangle \phi$$
 (Validity of sequents: quantification over all states)

How to express correctness for any initial value of program variable?

Not allowed: $\forall T \ i; \langle \dots i \dots \rangle \phi$ (program \neq logical variable)

Not intended: $\Rightarrow \langle \dots i \dots \rangle \phi$ (Validity of sequents: quantification over all states)

As previous: $\forall T i_0$; $(i_0 \doteq i \rightarrow \langle \dots i \dots \rangle \phi)$

How to express correctness for any initial value of program variable?

Not allowed:
$$\forall T \ i; \langle \dots i \dots \rangle \phi$$
 (program \neq logical variable)

Not intended:
$$\Rightarrow \langle \dots i \dots \rangle \phi$$
 (Validity of sequents: quantification over all states)

As previous:
$$\forall T i_0$$
; $(i_0 \doteq i \rightarrow \langle \dots i \dots \rangle \phi)$

Solution

Use explicit construct to record values in current state

Update
$$\forall T i_0; (\{i := i_0\} \langle \dots i \dots \rangle \phi)$$

Explicit State Updates

Updates specify computation state where formula is evaluated

Definition (Syntax of Updates)

If ${\bf v}$ is program variable, ${\bf t}$ FOL term type-compatible with ${\bf v}$, ${\bf t'}$ any FOL term, and ϕ any DL formula, then

- $\{v := t\}t'$ is DL term
- $\{v := t\} \phi$ is DL formula

Definition (Semantics of Updates)

State s interprets flexible symbols f with $\mathcal{I}_s(f)$

 β variable assignment for logical variables in t

$$ho(\{\mathtt{v}:=t\})(s)=s'$$
 where s' identical to s except $\mathcal{I}_{s'}(x)=\mathit{val}_{s,eta}(t)$

Explicit State Updates

Facts about updates $\{v := t\}$

- Update semantics identical to assignment
- Value of update depends on logical variables in t: use β
- Updates as "lazy" assignments (no term substitution done)
- Updates are not assignments: right-hand side is FOL term
 {x := n}φ cannot be turned into assignment (n logical variable)
 ⟨x=i++;⟩φ cannot directly be turned into update
- Updates are not equations: change value of flexible terms

Computing Effect of Updates (Automatic)

Rewrite rules for update followed by ...

Update computation delayed until p symbolically executed

Assignment Rule Using Updates

Symbolic execution of assignment using updates

$$\frac{\Gamma \Longrightarrow \{\mathtt{x} := t\} \langle \mathtt{rest} \rangle \phi, \Delta}{\Gamma \Longrightarrow \langle \mathtt{x} = \mathtt{t}; \ \mathtt{rest} \rangle \phi, \Delta}$$

- Avoids renaming of program variables
- Works as long as t has no side effects (ok in simple DL)

Demo

Examples/lect11/swap.key

Example Proof

Example

```
\programVariables {
  int x;
}
\problem {
  (\exists int y;
    ({x := y}\<{while (x > 0) {x = x-1;}}\> x=0 ))
}
Intuitive Meaning? Satisfiable? Valid?
```

Demo

Examples/lect11/term.key

Example Proof

Example

```
\programVariables {
  int x;
}
\problem {
  (\exists int y;
     ({x := y}\<{while (x > 0) {x = x-1;}}\> x=0 ))
}
```

Intuitive Meaning? Satisfiable? Valid?

Demo

Examples/lect11/term.key

What to do when we cannot determine a concrete loop bound?

How to apply updates on updates?

Example

Symbolic execution of

yields:

$${x := x+y}{y := x-y}{x := x-y}$$

Need to compose three sequential state changes into a single one!

Definition (Parallel Update)

A parallel update is expression of the form $\{l_1 := v_1 || \cdots || l_n := v_n\}$ where each $\{l_i := v_i\}$ is simple update

- All v_i computed in old state before update is applied
- \bullet Updates of all locations I_i executed simultaneously
- Upon conflict $l_i = l_j$, $v_i \neq v_j$ later update $(\max\{i,j\})$ wins

Definition (Parallel Update)

A parallel update is expression of the form $\{l_1 := v_1 || \cdots || l_n := v_n\}$ where each $\{l_i := v_i\}$ is simple update

- All v_i computed in old state before update is applied
- Updates of all locations l_i executed simultaneously
- Upon conflict $l_i = l_j$, $v_i \neq v_j$ later update $(\max\{i,j\})$ wins

Definition (Composition Sequential Updates/Conflict Resolution)

$$\{I_1 := r_1\} \{I_2 := r_2\} = \{I_1 := r_1 | I_2 := \{I_1 := r_1\} r_2\}$$

$$\{I_1 := v_1 | | \cdots | | I_n := v_n\} x = \begin{cases} x & \text{if } x \notin \{I_1, \dots, I_n\} \\ v_k & \text{if } x = I_k, x \notin \{I_{k+1}, \dots, I_n\} \end{cases}$$

Example

```
(\{x := x+y\}\{y := x-y\})\{x := x-y\} = \{x := x+y \mid | y := (x+y)-y\}\{x := x-y\} = \{x := x+y \mid | y := (x+y)-y \mid | x := (x+y)-((x+y)-y)\} = \{x := x+y \mid | y := x \mid | x := y\} = \{y := x \mid | x := y\}
```

KeY automatically deletes overwritten (unnecessary) updates

Demo

Examples/lect11/swap.key

Example

```
(\{x := x+y\}\{y := x-y\})\{x := x-y\} = \{x := x+y \mid | y := (x+y)-y\}\{x := x-y\} = \{x := x+y \mid | y := (x+y)-y \mid | x := (x+y)-((x+y)-y)\} = \{x := x+y \mid | y := x \mid | x := y\} = \{y := x \mid | x := y\}
```

KeY automatically deletes overwritten (unnecessary) updates

Demo

Examples/lect11/swap.key

Parallel updates to store intermediate state of symbolic computation

A Warning

First-order rules that substitute arbitrary terms

$$\exists -\mathsf{right} \ \frac{\Gamma \Longrightarrow [\mathsf{x}/t'] \ \phi, \ \exists \ T \ \mathsf{x}; \ \phi, \Delta}{\Gamma \Longrightarrow \exists \ T \ \mathsf{x}; \ \phi, \Delta} \quad \forall -\mathsf{left} \ \frac{\Gamma, \forall \ T \ \mathsf{x}; \ \phi, \ [\mathsf{x}/t'] \ \phi \Longrightarrow \Delta}{\Gamma, \forall \ T \ \mathsf{x}; \ \phi \Longrightarrow \Delta}$$

$$\text{applyEq} \ \frac{\Gamma, t \doteq t', [t/t'] \, \psi \Longrightarrow [t/t'] \, \phi, \Delta}{\Gamma, t \doteq t', \psi \Longrightarrow \phi, \Delta}$$

t, t' must be rigid, because all occurrences must have the same value

Example

$$\frac{\Gamma, \mathbf{i} \doteq 0 \rightarrow \langle \mathbf{i} + + \rangle \mathbf{i} \doteq 0 \Longrightarrow \Delta}{\Gamma, \forall T \times ; (x \doteq 0 \rightarrow \langle \mathbf{i} + + \rangle \times \doteq 0) \Longrightarrow \Delta}$$

Logically valid formula would result in unsatisfiable antecedent! KeY prohibits unsound substitutions

Outline

- DL Syntax
 - State Dependence
 - Signature
 - Terms
 - Atomic Programs
 - DL Programs
 - Program Formulas
- DL Semantics
 - States
 - Kripke Structures
 - Program Formula Valuation
 - Program Correctness
- Operational Semantics
- Symbolic Execution
 - Updates
 - Parallel Updates
 - Restrictions

Literature for this Lecture

Essential

KeY Book Verification of Object-Oriented Software, Chapter 10: Using KeY

KeY Book Verification of Object-Oriented Software, Chapter 3: Dynamic Logic (Sections 3.1, 3.2, 3.4, 3.5, 3.6.1, 3.6.3, 3.6.4)